

Improving the Accuracy of Computed
Eigenvalues
Using 32 and 64 bit floating point arithmetic

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Eigenvalues



- ◆ Given a matrix A and its eigenvalue, eigenvector pair λ, x are by definition $Ax = \lambda x$
- ◆ A standing wave in a rope fixed at its boundaries can be seen as an example of an eigenvector, or more precisely, an eigenfunction of the transformation corresponding to the passage of time.



Singing Water Goblet

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The Problem

- ◆ **Want to solve**

$$Ax = \lambda x$$

- ◆ **But on a computer we make errors and don't get λ, x exactly, but there exists μ, y such that**

$$A(x + y) = (\lambda + \mu)(x + y)$$

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Given λ & x can we find μ & y

$$A(x + y) = (\lambda + \mu)(x + y)$$

Expanding things

$$Ax + Ay = \lambda x + \lambda x + \mu x + \mu y$$

Rearranging things

$$(A - \lambda I)y - \mu x = \underline{\lambda x - Ax} + \mu y$$

$$(A - \lambda I)y - \mu x = r + \mu y$$

Term is square
of error, will ignore

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We have $(A - \lambda I)y - \mu x = r$

- ◆ At the moment we have **$n+1$** unknowns μ, y and **n** equations.
- ◆ Need one more equation.
- ◆ Eigenvectors can be normalized, we will choose $x_s = 1$, s is arbitrary.
- ◆ This imposes another constraint on the problem.
 - **$n+1$ unknowns and $n+1$ equations**

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We Have $(A - \lambda I)y - \mu x = r$

- ◆ Rewrite the equation in matrix form with the constraint $x_s = 1$ or $y_s = 0$.

$$\begin{pmatrix} A - \lambda I & -x \\ e_s^T & 0 \end{pmatrix} \begin{pmatrix} y \\ \mu \end{pmatrix} = \begin{pmatrix} r \\ 0 \end{pmatrix}$$

$$e_s = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \leftarrow \text{S element}$$

$$e_s^T y = 0$$

μy Is a term in the error squared
We will ignore it.

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We Have a Symmetric Eigenvalue Problem

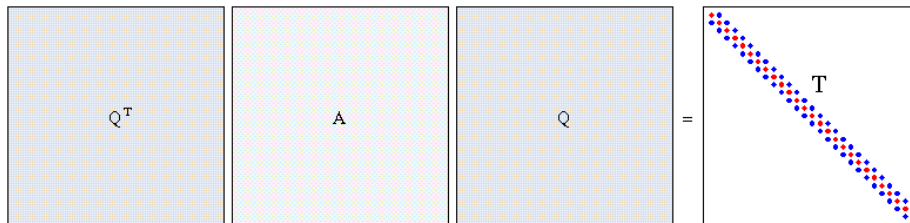
- ◆ For a symmetric eigenvalue problem the eigenvalues are real and the eigenvectors are orthogonal.
- ◆ The matrix, A , can be reduced to a similar form, tridiagonal.
- ◆ The reduction is done by a sequence of orthogonal transformations, called Q .

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Reduction to Tridiagonal Form

$$Q^T A Q = T$$



$$\text{cost} : \approx \frac{4}{3} n^3 \text{ flops}$$

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- ◆ Let say we have computed the reduction to tridiagonal form
 - We will do this in 32 bit arithmetic
 - $O(n^3)$ ops
- ◆ $Q^T A Q = T$

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At This Stage...

- ◆ We have the reduction to tridiagonal form
 - $Q^T A Q = T$
- ◆ And we compute the eigenvalues of T in 32 bit floating point arithmetic.
- ◆ Now we want to compute a more accurate eigenvalue and an eigenvector

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$$\begin{pmatrix} A - \lambda I & -x \\ e_s^T & 0 \end{pmatrix} \begin{pmatrix} y \\ \mu \end{pmatrix} = \begin{pmatrix} r \\ 0 \end{pmatrix}$$


- ◆ Multiplying by Q^T on both sides and using
 - $Q^T A Q = T$ and
 - $Q^T Q = Q Q^T = I$

$$\begin{pmatrix} Q^T & \\ & 1 \end{pmatrix} \begin{pmatrix} A - \lambda I & -x \\ e_s^T & 0 \end{pmatrix} \begin{pmatrix} Q & \\ & 1 \end{pmatrix} \begin{pmatrix} Q^T & \\ & 1 \end{pmatrix} \begin{pmatrix} y \\ \mu \end{pmatrix} = \begin{pmatrix} Q^T & \\ & 1 \end{pmatrix} \begin{pmatrix} r \\ 0 \end{pmatrix}$$

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Identity

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$$\begin{pmatrix} Q^T \\ 1 \end{pmatrix} \begin{pmatrix} A - \lambda I & -x \\ e_s^T & 0 \end{pmatrix} \begin{pmatrix} Q \\ 1 \end{pmatrix} \begin{pmatrix} Q^T \\ 1 \end{pmatrix} \begin{pmatrix} y \\ \mu \end{pmatrix} = \begin{pmatrix} Q^T \\ 1 \end{pmatrix} \begin{pmatrix} r \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} T - \lambda I & -Q^T x \\ e_s^T Q & 0 \end{pmatrix} \begin{pmatrix} Q^T y \\ \mu \end{pmatrix} = \begin{pmatrix} Q^T r \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_1 & \beta_2 & & & * \\ \beta_2 & \alpha_2 & \beta_3 & & * \\ & \ddots & \ddots & \ddots & \vdots \\ & & \beta_{n-1} & \alpha_{n-1} & \beta_n & * \\ & & & \beta_n & \alpha_n & * \\ * & * & * & * & * & 0 \end{pmatrix}$$

- ◆ The matrix is a rank 2 modification of a tridiagonal matrix.
- ◆ Easy to solve

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Approach

- ◆ Reduce the matrix to tridiagonal form in single precision.
- ◆ Compute the eigenvalues in single precision.
- ◆ Solve the tridiagonal system in an iterative step to improve the accuracy of the eigenvalue and compute the eigenvector.
 - Do this for each eigenvalue, eigenvector pair
- ◆ Process is equivalent to Newton's method
 - Quadratic convergence
- ◆ Requires 1.5 X the storage (one copy of the matrix in double precision and another in single precision)

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Algorithm (For each eigenpair)

◆ Reduce the matrix A to tridiagonal form T with a set of transformations Q

◆ Compute the eigenvalues of A

```
❖  $T = Q^T A Q$  %Reduce the matrix to tridiagonal form SINGLE  $O(n^3)$ 
❖  $\Lambda = \text{eig}(T)$  % Find the eigenvalues of  $T$  SINGLE  $O(n^2)$ 
❖  $r = \lambda x - Ax$  % Residual DOUBLE  $O(n^2)$  with random  $x$ 
❖ Form  $B = \begin{pmatrix} T - \lambda I, & -Q^T x \\ e^T_s Q, & 0 \end{pmatrix}$  % SINGLE  $O(n^2)$ 
❖  $(L,U)=LU(B)$  % Factor the matrix  $B$  SINGLE  $O(n)$ 
❖ while (  $\|r\|$  not small enough ), %stopping criteria
    ❖  $z = L \setminus (U \setminus r)$  %LU factorization on the residual SINGLE  $O(n)$ 
    ❖  $x = x + Qz_{1:n}$  % new solution DOUBLE  $O(n^2)$ 
    ❖  $\lambda = \lambda + z_{n+1}$  % new solution DOUBLE  $O(1)$ 
    ❖  $r = Q^T(\lambda x - Ax)$  % new residual DOUBLE  $O(n^2)$ 
❖ end
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