

ADAPT: An Event-Based Adaptive Collective Communication Framework

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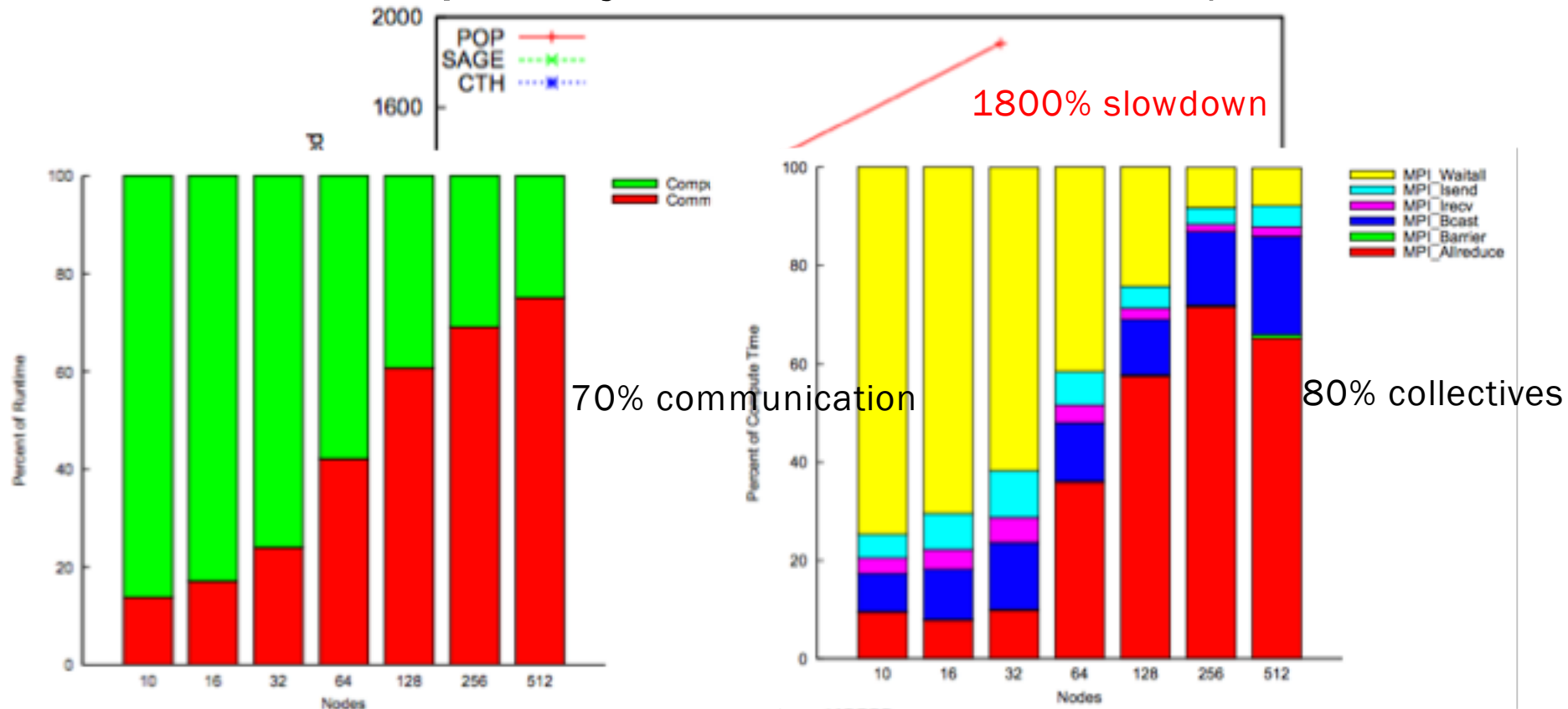


The performance of collective operations

- Application performance is directly linked with communication performance
 - Point-to-point (two-sided and one-sided)
 - Collective operations
- What impacts the performance of collectives
 - Underlying algorithms
 - P2P performance
 - Noise (any thing can delay a function call)
 - Network topologies (and mapping strategies)
 -

Propagation of noise

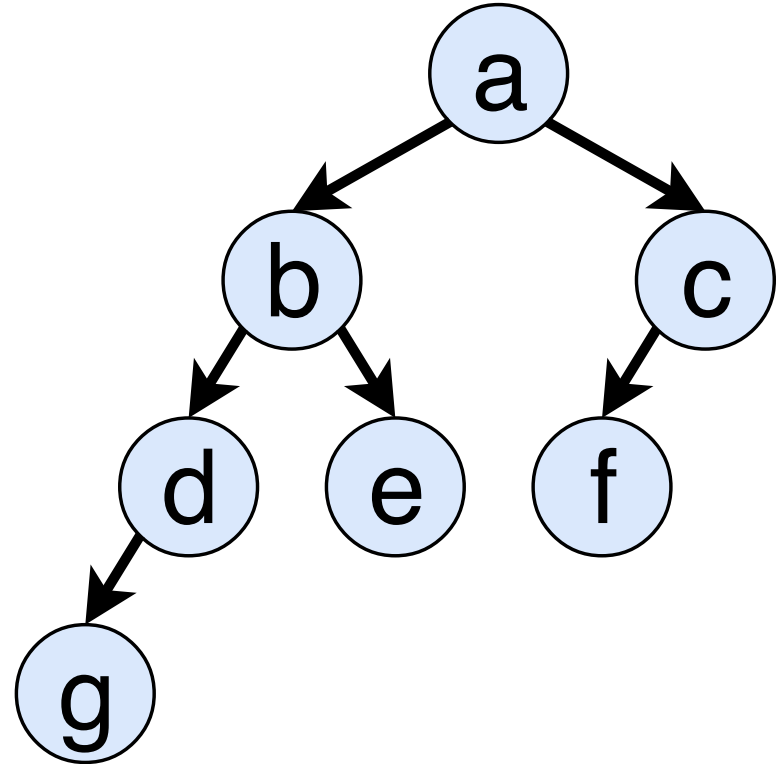
Application Performance with 2.5% noise (10 Hz frequency and 2.5 ms detour)



K. B. Ferreira, P. Bridges, and R. Brightwell. 2008. Characterizing application sensitivity to OS interference using kernel-level noise injection.

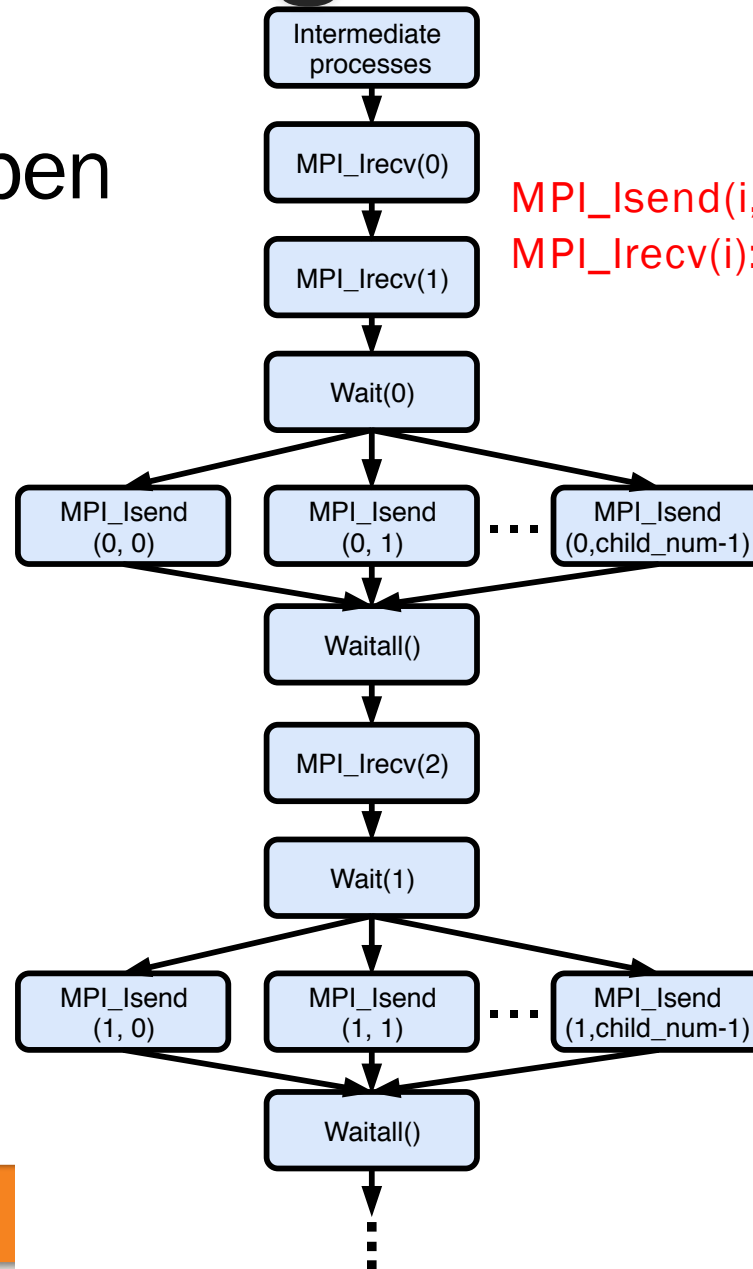
MPI_Bcast

- Collective is based on Point-to-point(P2P).
- Propagate messages from root to all the other processes.
- Apply pipelining for big messages.
 - Divided messages into small segments.
 - Segments are propagated one by one.
- Focus on intermediate.



MPI_Bcast using non-blocking P2P

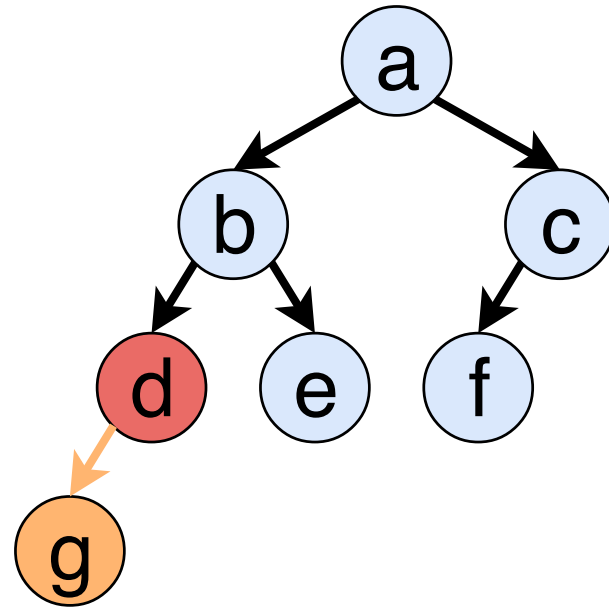
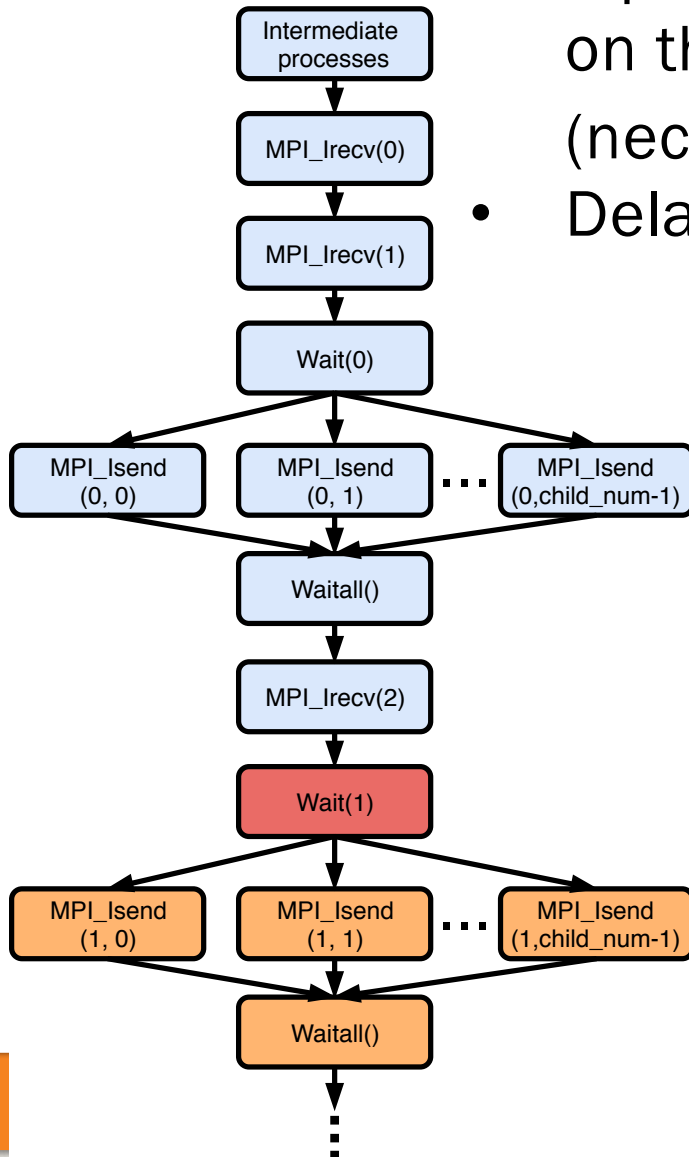
- Default in Open MPI



MPI_Isend(i, j): Send segment i to child j
MPI_Irecv(i): Recv segment i

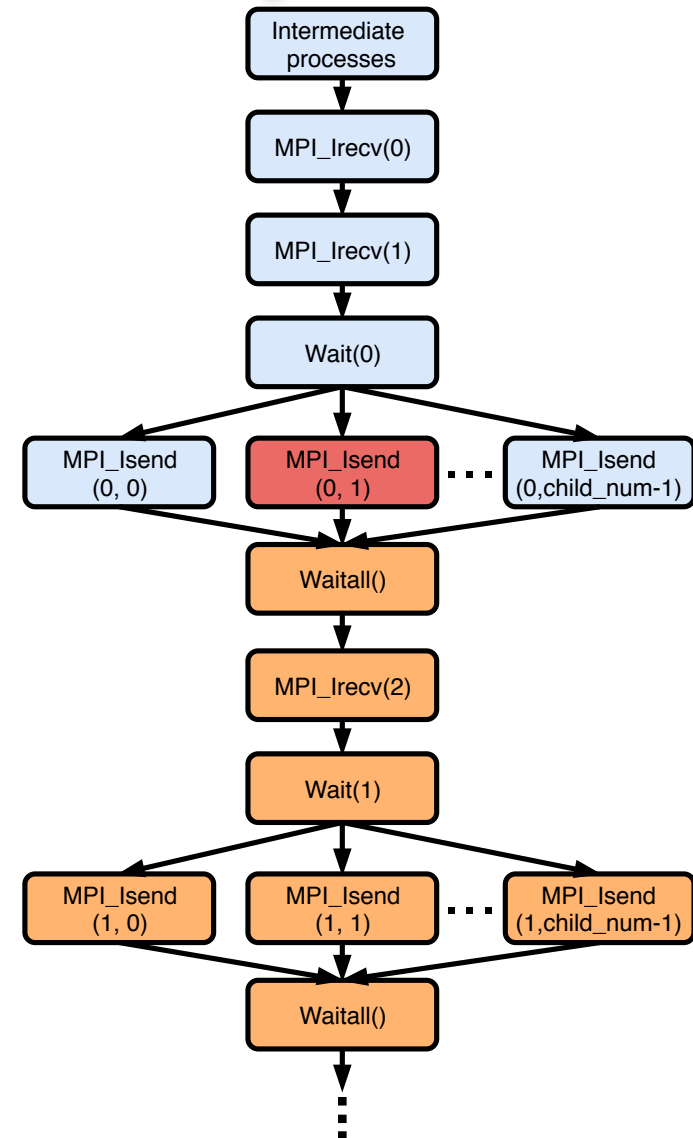
Data dependency

- Input data of some P2P routines depends on the output data of other P2P routines. (necessary)
- Delay



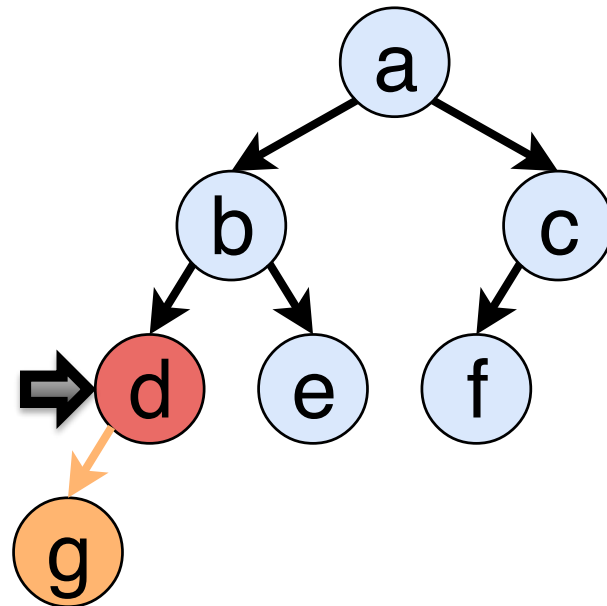
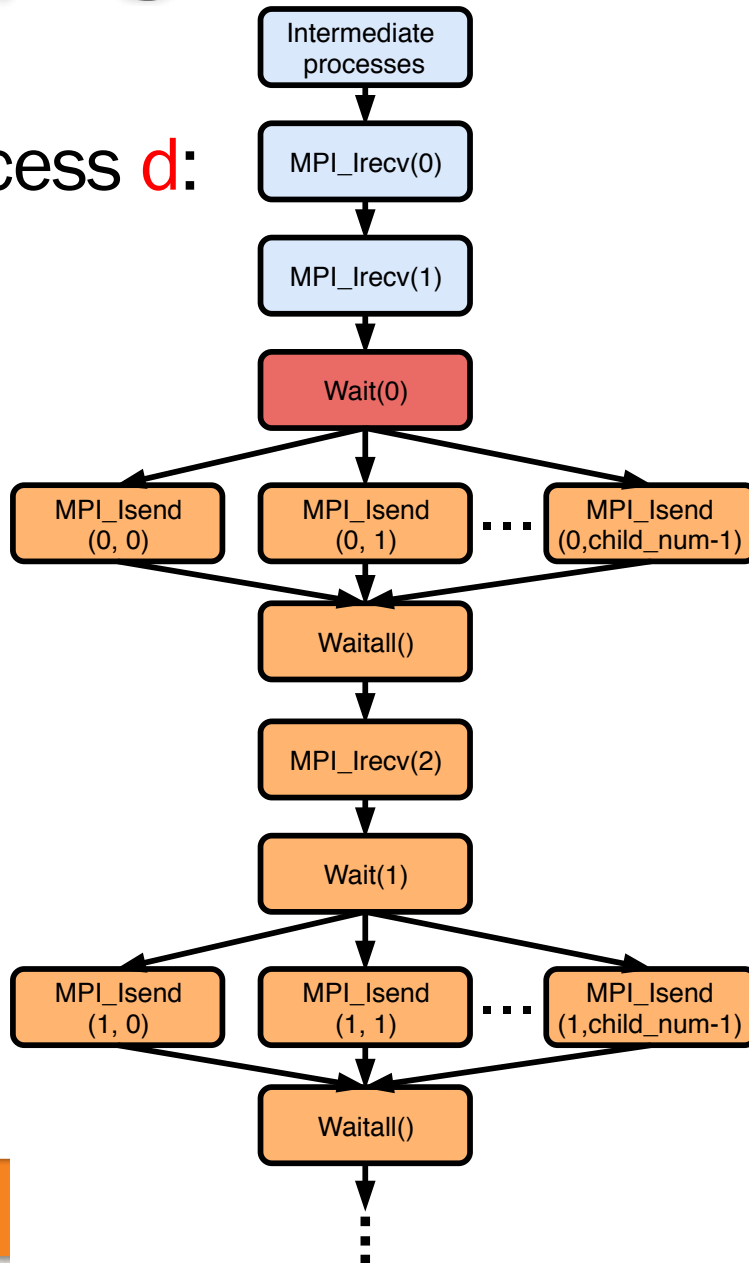
Synchronization dependency

- Caused by synchronizations between P2P routines. (unnecessary)
- Waitall and Wait act as synchronizations that order P2P routines between them.
 - Segment (in order)
- Delay



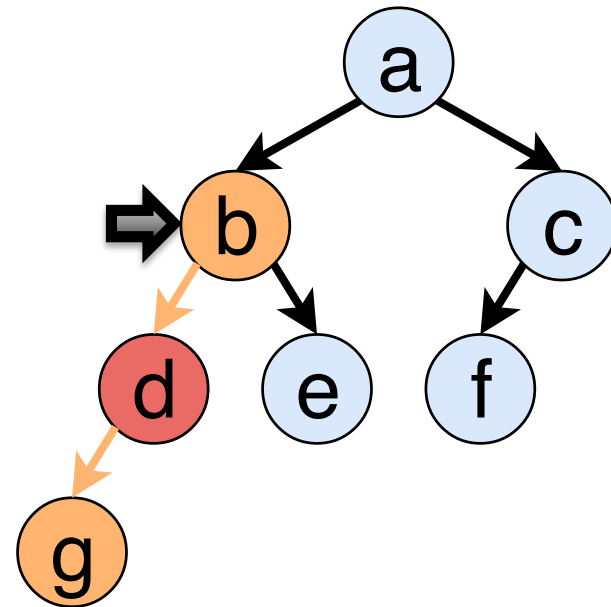
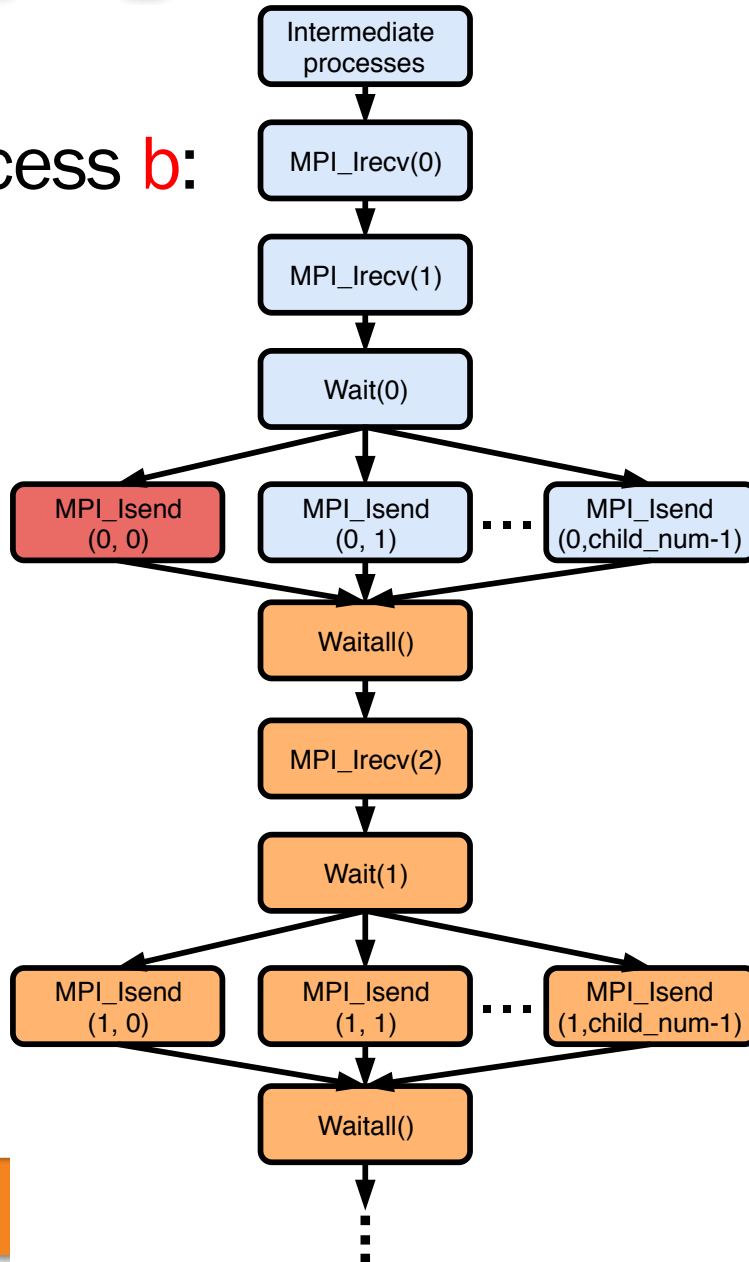
Propagation of noise

On process **d**:



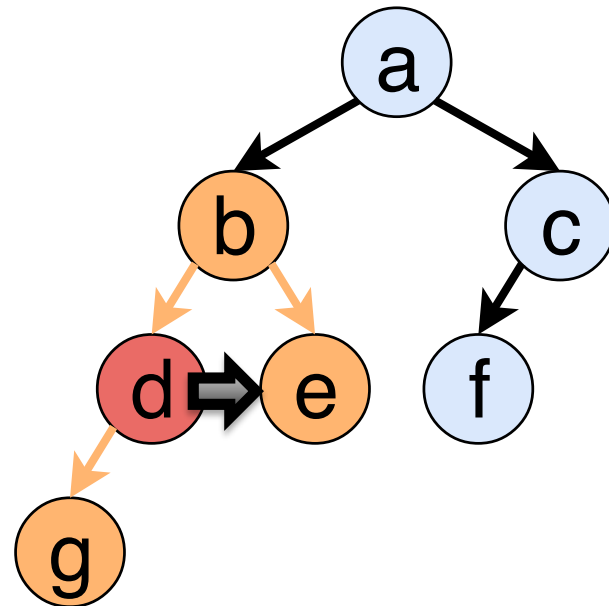
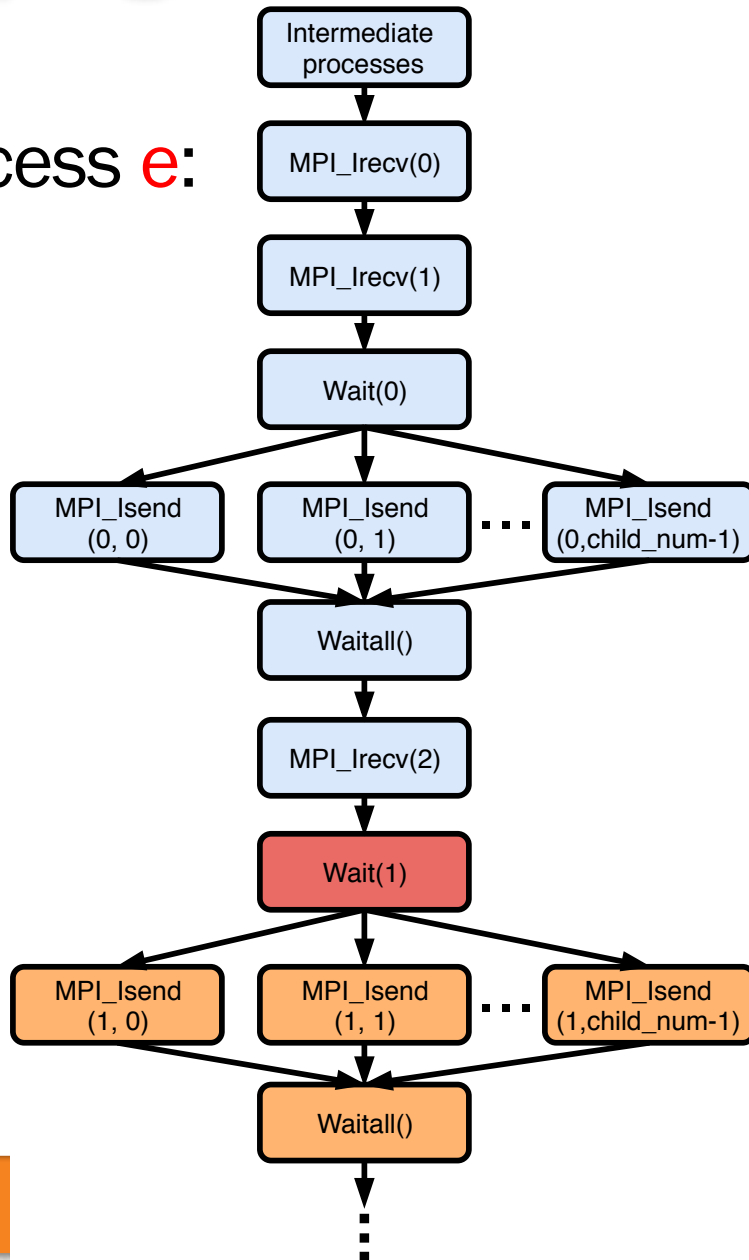
Propagation of noise

On process **b**:



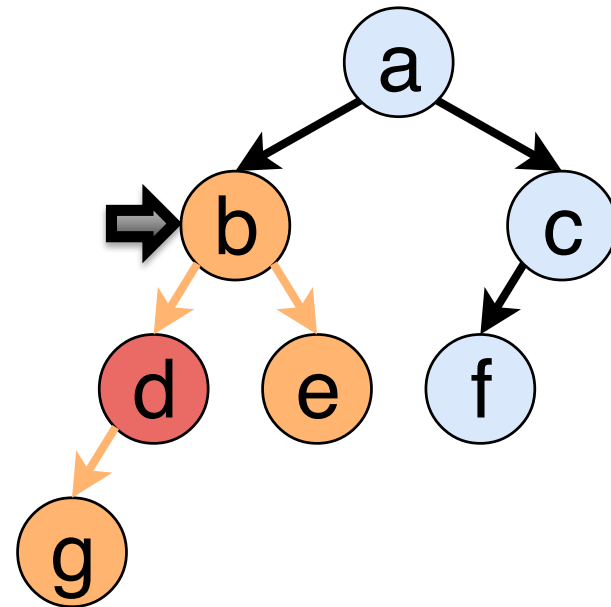
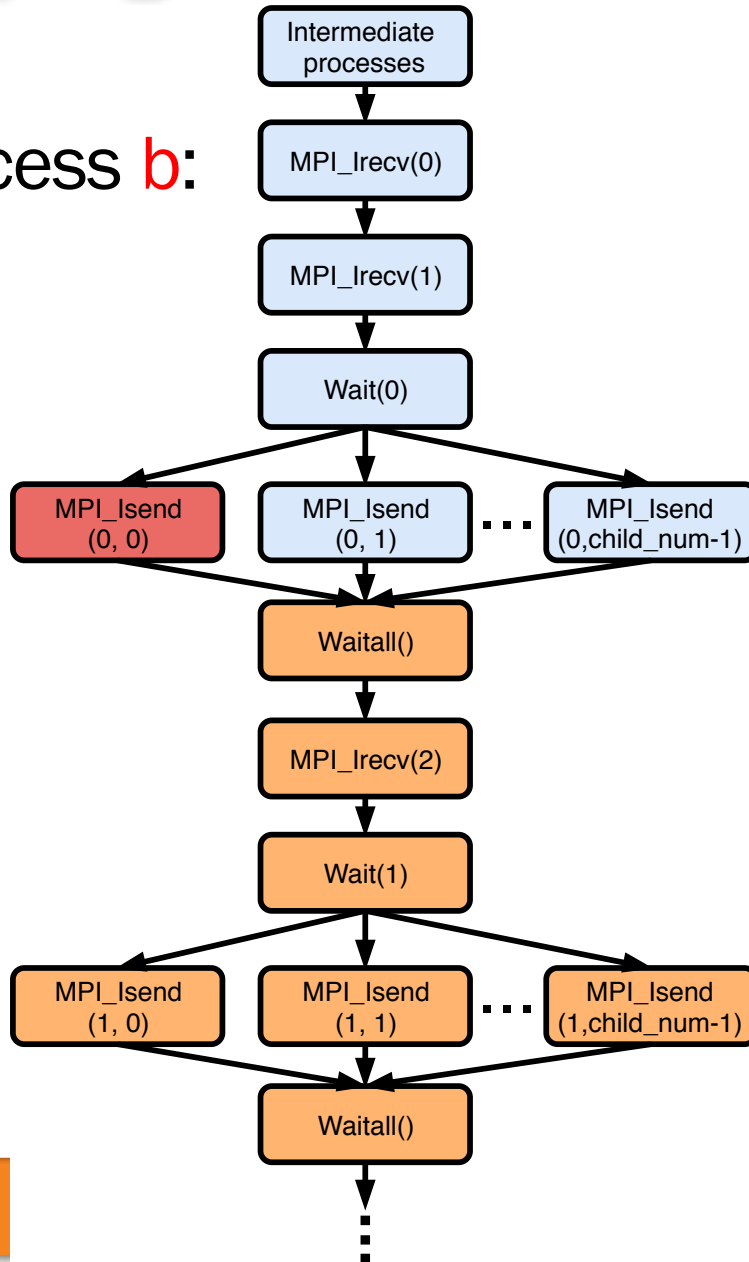
Propagation of noise

On process **e**:



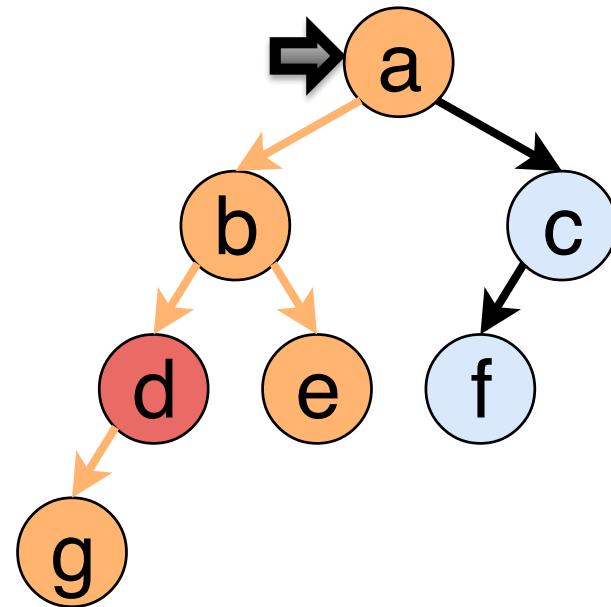
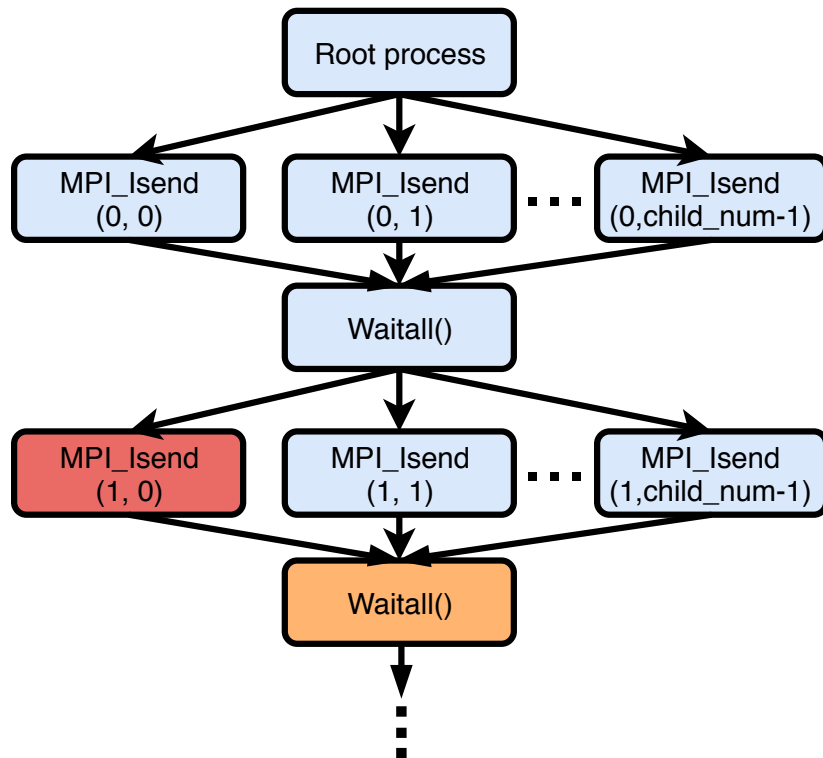
Propagation of noise

On process **b**:



Propagation of noise

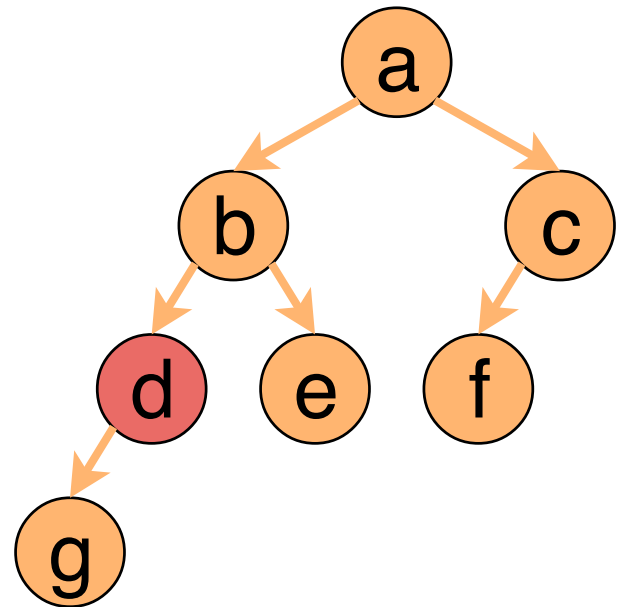
On process **a**:



Propagation of noise

Summary:

- Segment (in order)
- One process will delay all the processes



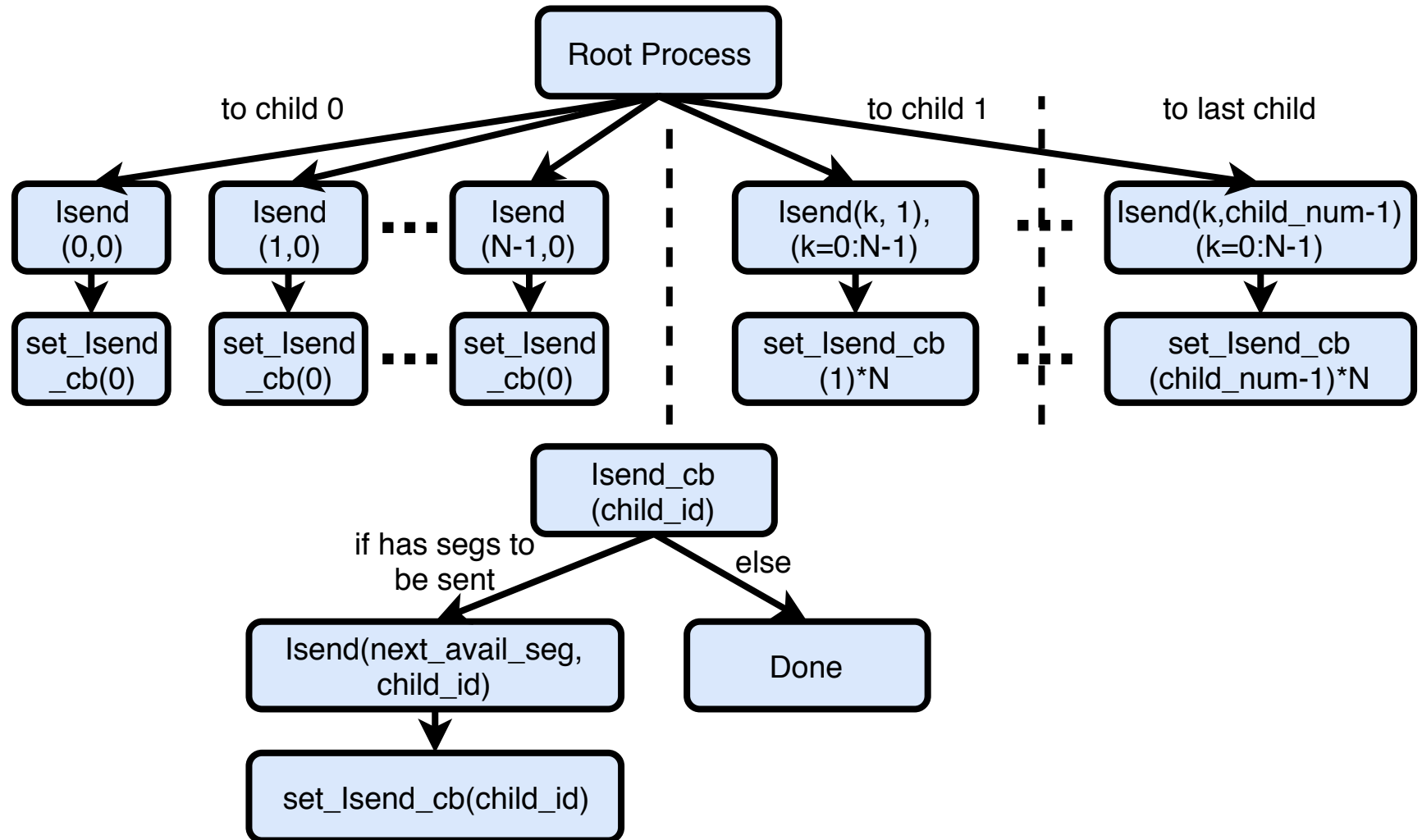
Event-driven Design

- Event-driven programming is a long existing programming model.
 - Event driven I/O.
 - Embedded systems.
 - Mobile networks.
 - Server applications.
- An event loop to detect events.
- When an event occurs, the corresponding callback is triggered.

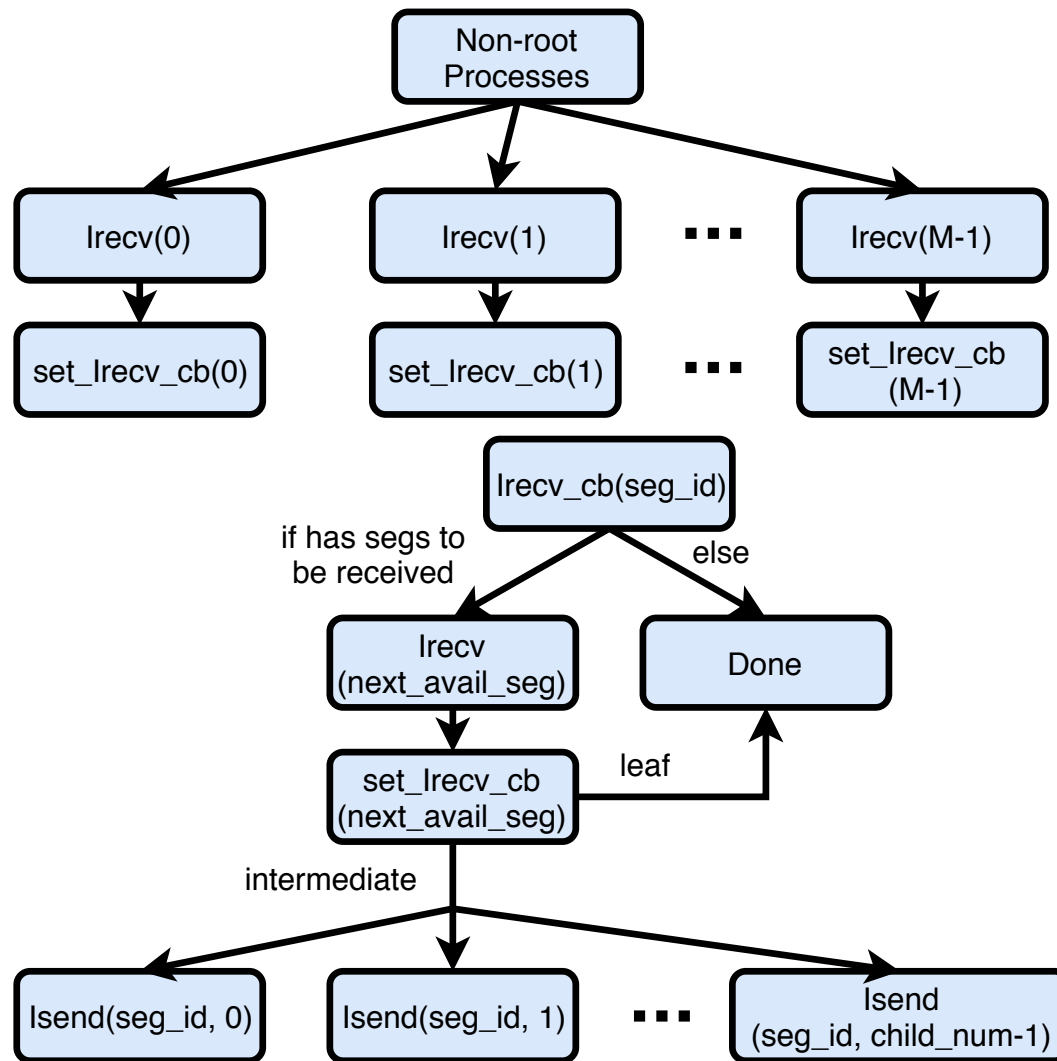
ADAPT

- Design collective operations with events and callbacks.
 - Eliminate the need to wait for separate P2P to complete.
 - Relax the synchronizations.
- Event loop: Open MPI progress engine.
- Events: the completion of non-blocking P2P routines.
- Callbacks: analyze the state of the collective algorithms, and post new non-blocking P2P if necessary.
- Using lower level non-blocking P2P.

MPI_Bcast in ADAPT (root)

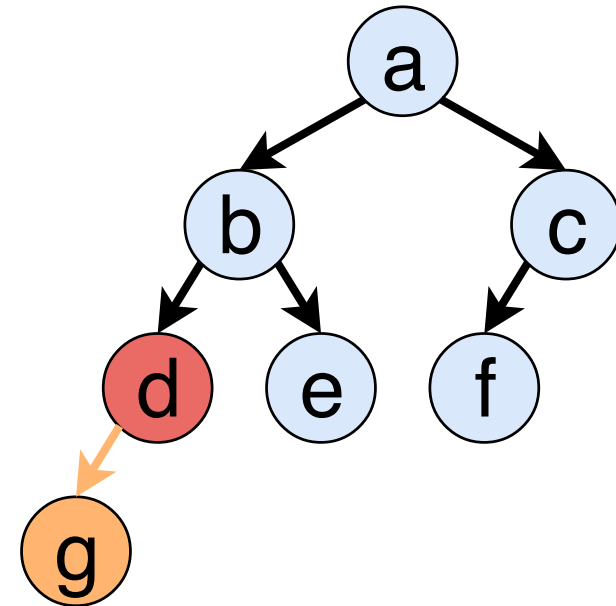
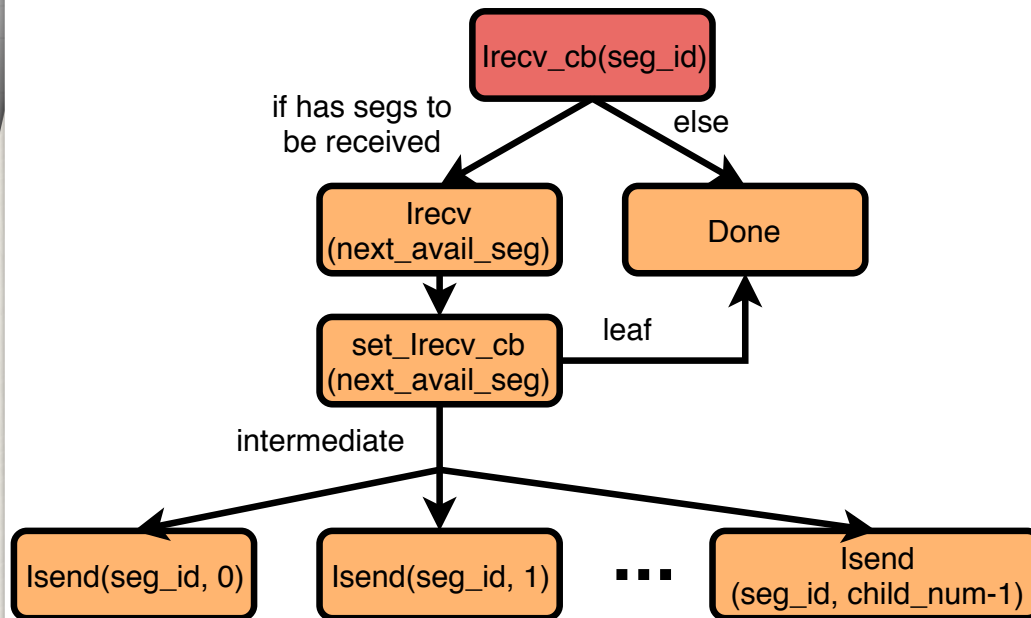


MPI_Bcast in ADAPT (non-root)



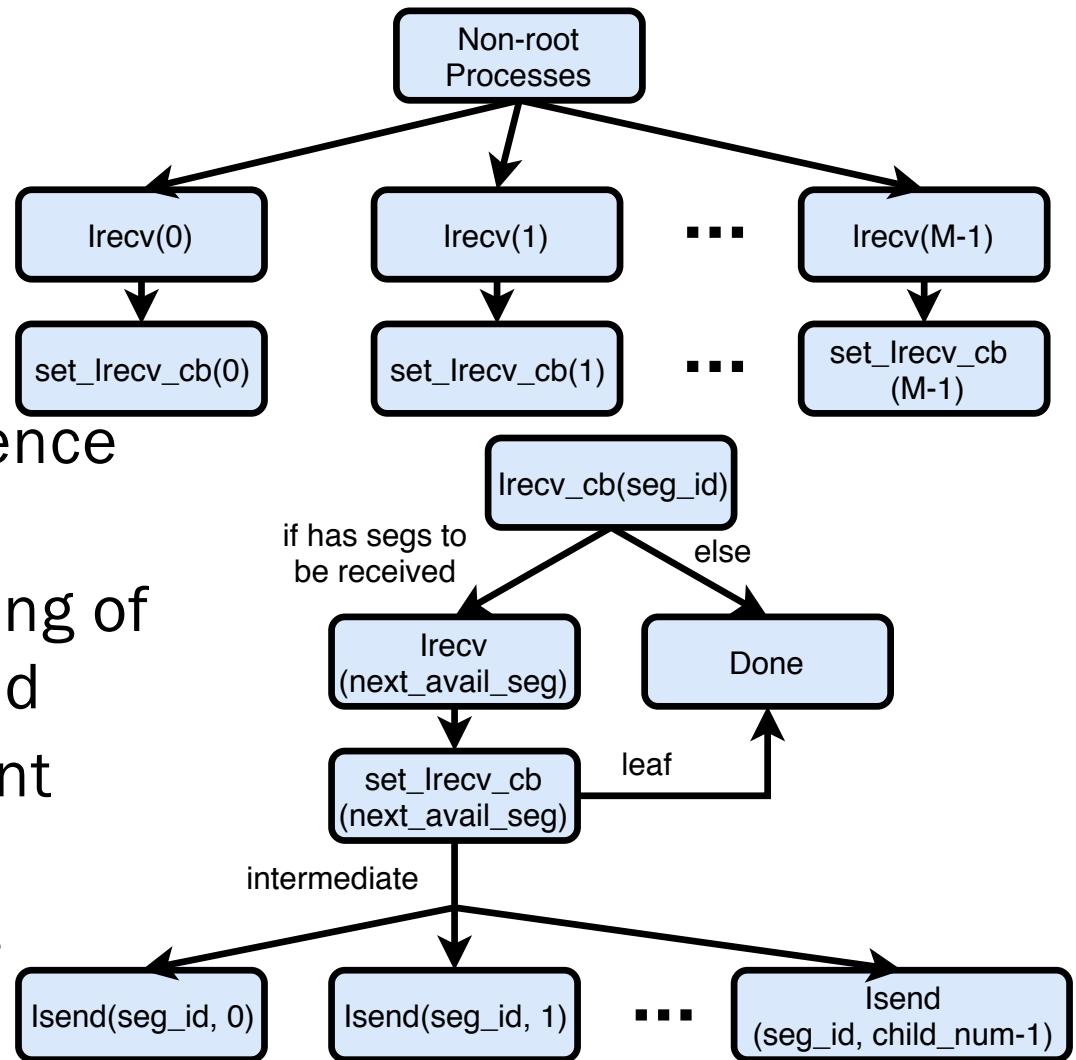
Data dependency

- same as previous implementations.



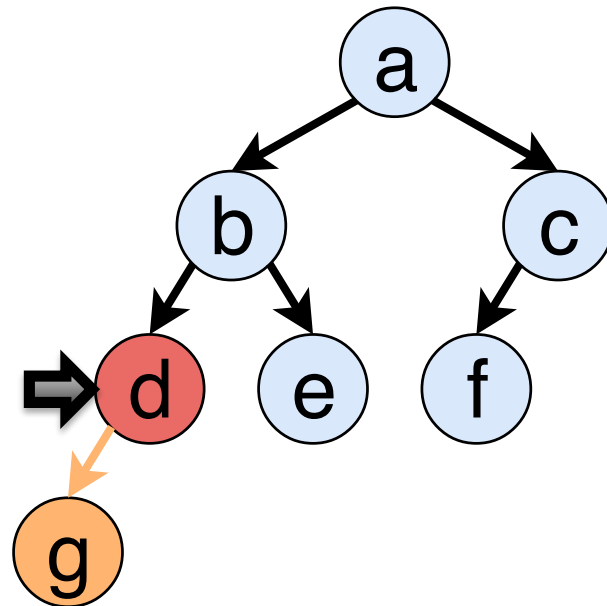
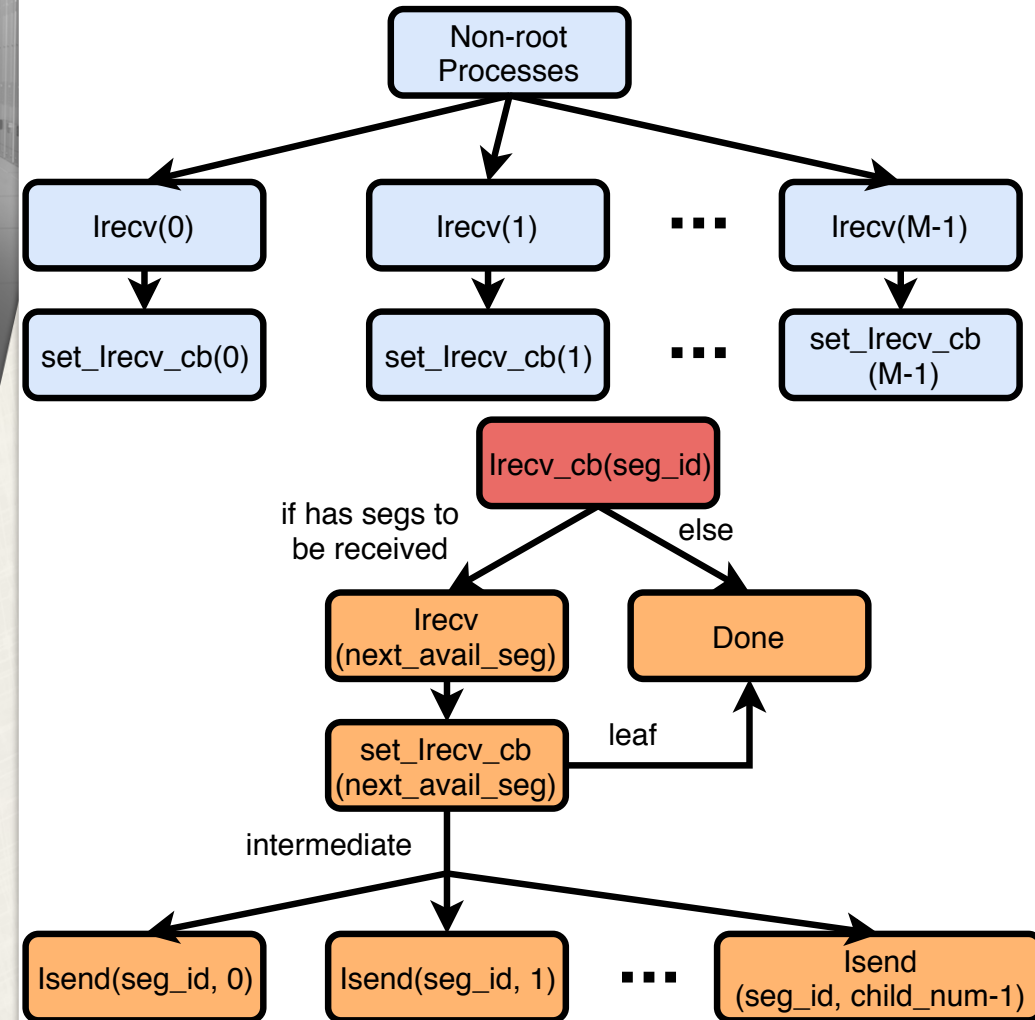
Synchronization dependency

- Segment independence
 - Rebalance
 - Decouple receiving of next segment and sending of current segment
- Child independence



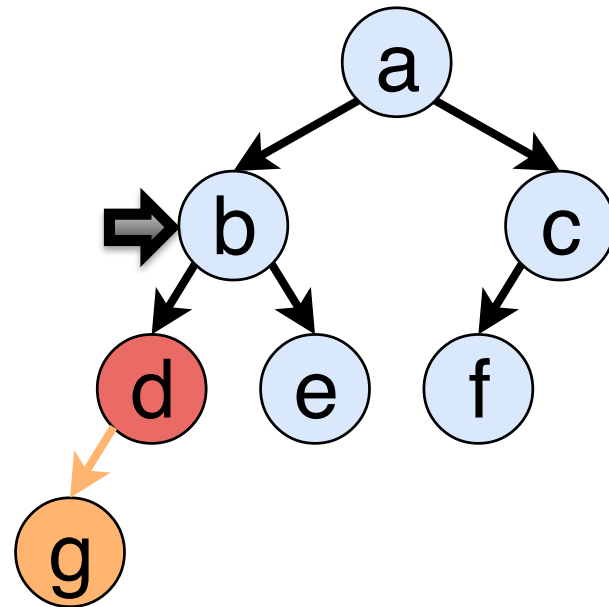
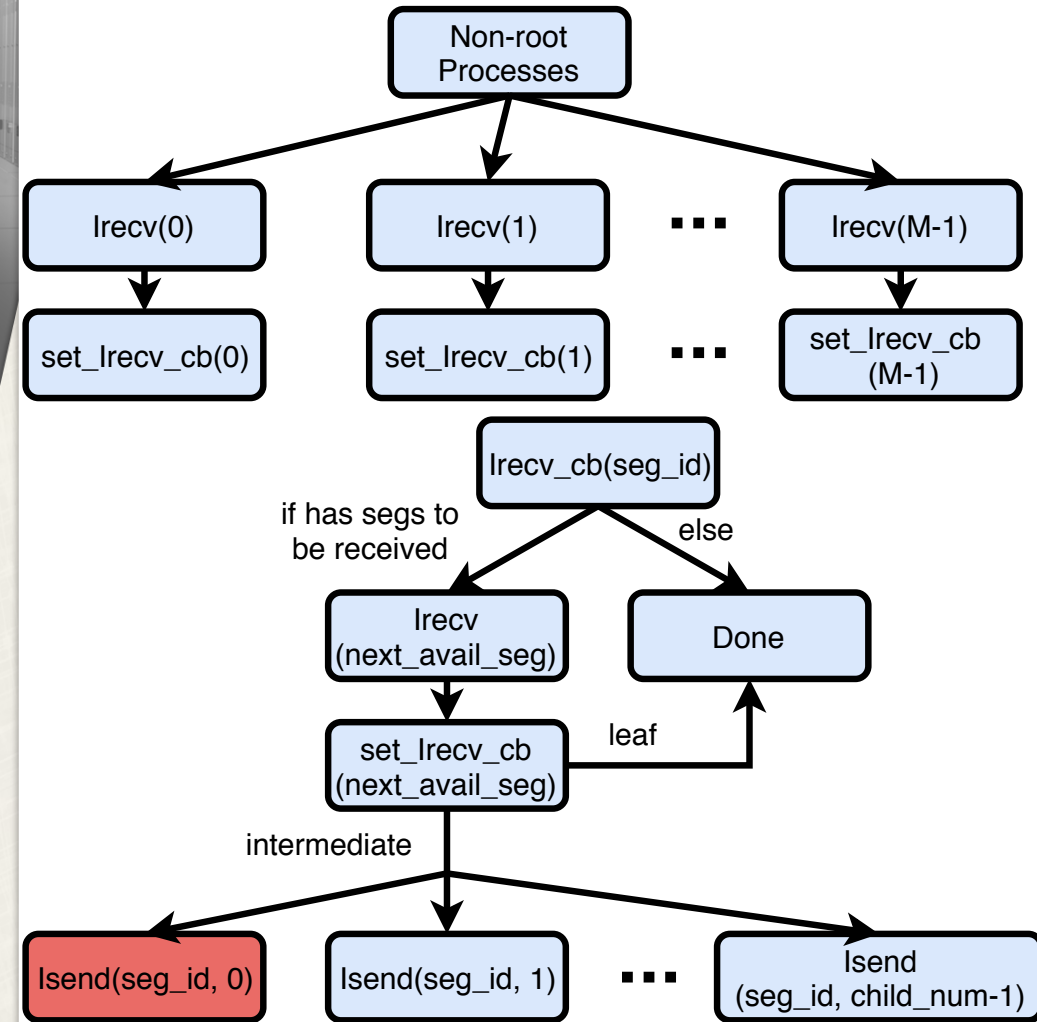
Propagation of noise

On process **d**:



Propagation of noise

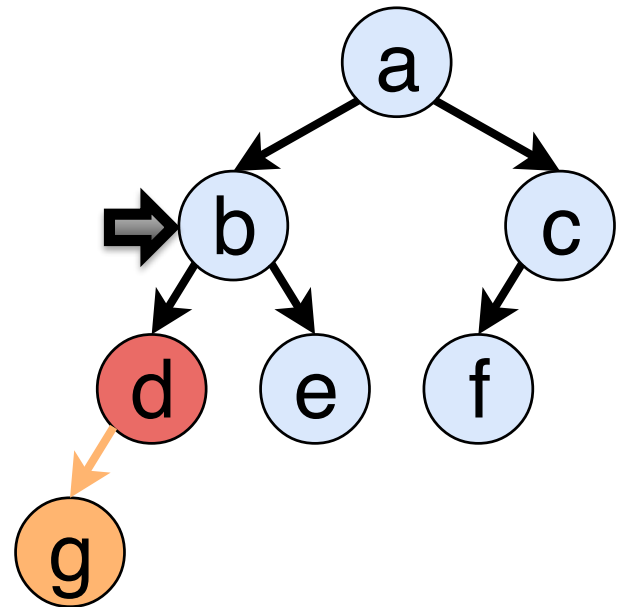
On process **b**:



Propagation of noise

Summary:

- Segment independence
- Child independence
- One process will only delay its descendants



Extend to other collective operations

General Problem: Issue multiple send/recv

Algorithm 1: Blocking P2P Implementation

```
1 for  $i \leftarrow 0$  to  $k$  do
2   MPI_Send( $i$ )/MPI_Recv( $i$ );
```

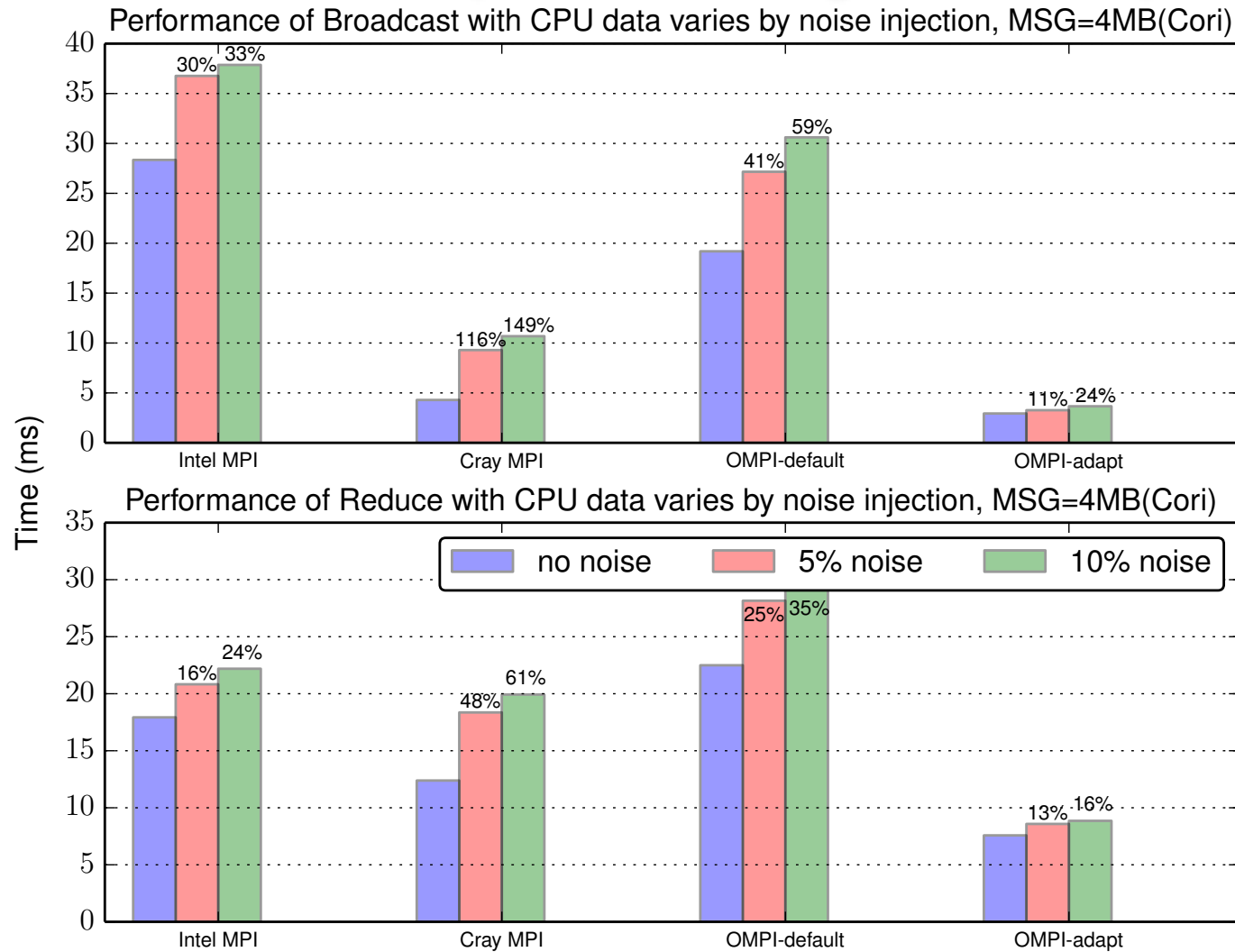
Algorithm 2: Nonblocking P2P Implementation

```
1 for  $i \leftarrow 0$  to  $k$  do
2   MPI_Isend( $i$ )/MPI_Irecv( $i$ );
3 Waitall();
```

Algorithm 3: Adapt Implementation

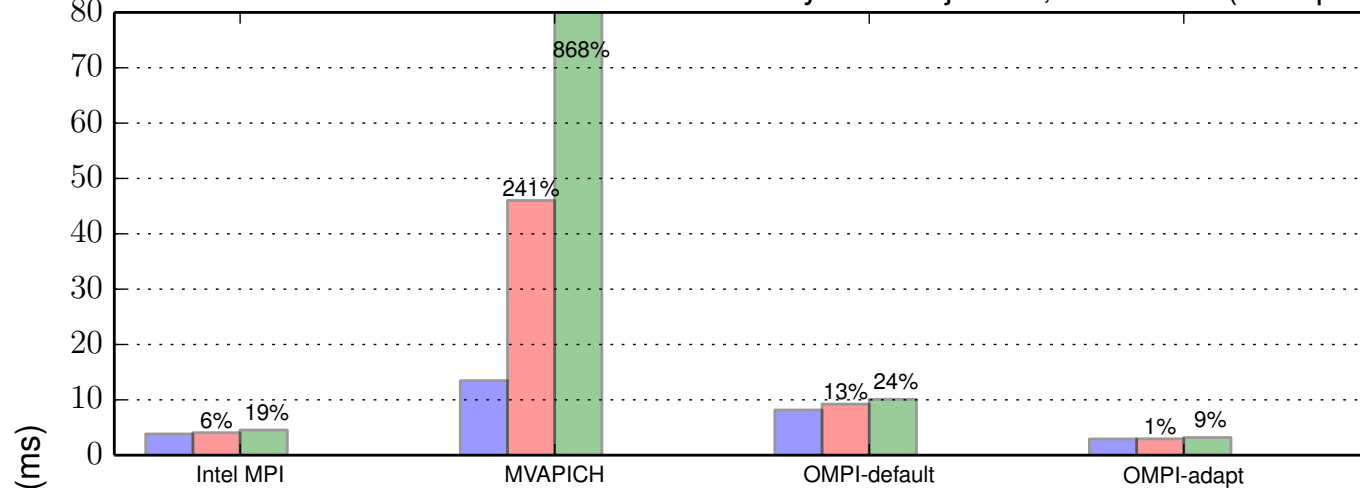
```
1 for  $i \leftarrow 0$  to  $k$  do
2   Isend( $i$ )/Irecv( $i$ );
3   set_Isend_cb( $i$ )/set_Irecv_cb( $i$ );
```

Experiments (noise injection)

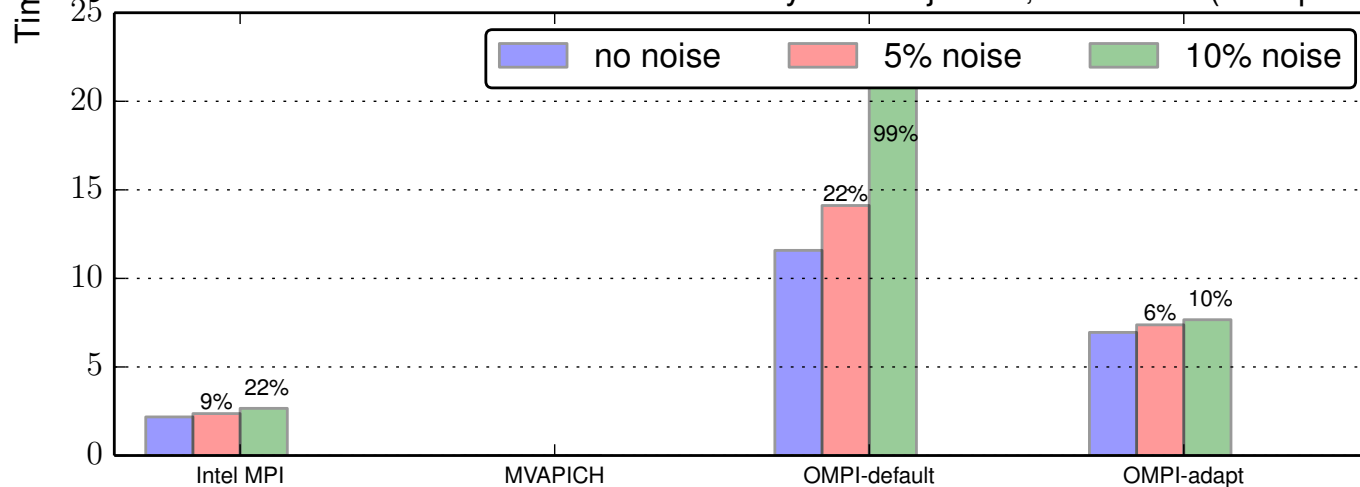


Experiments (noise injection)

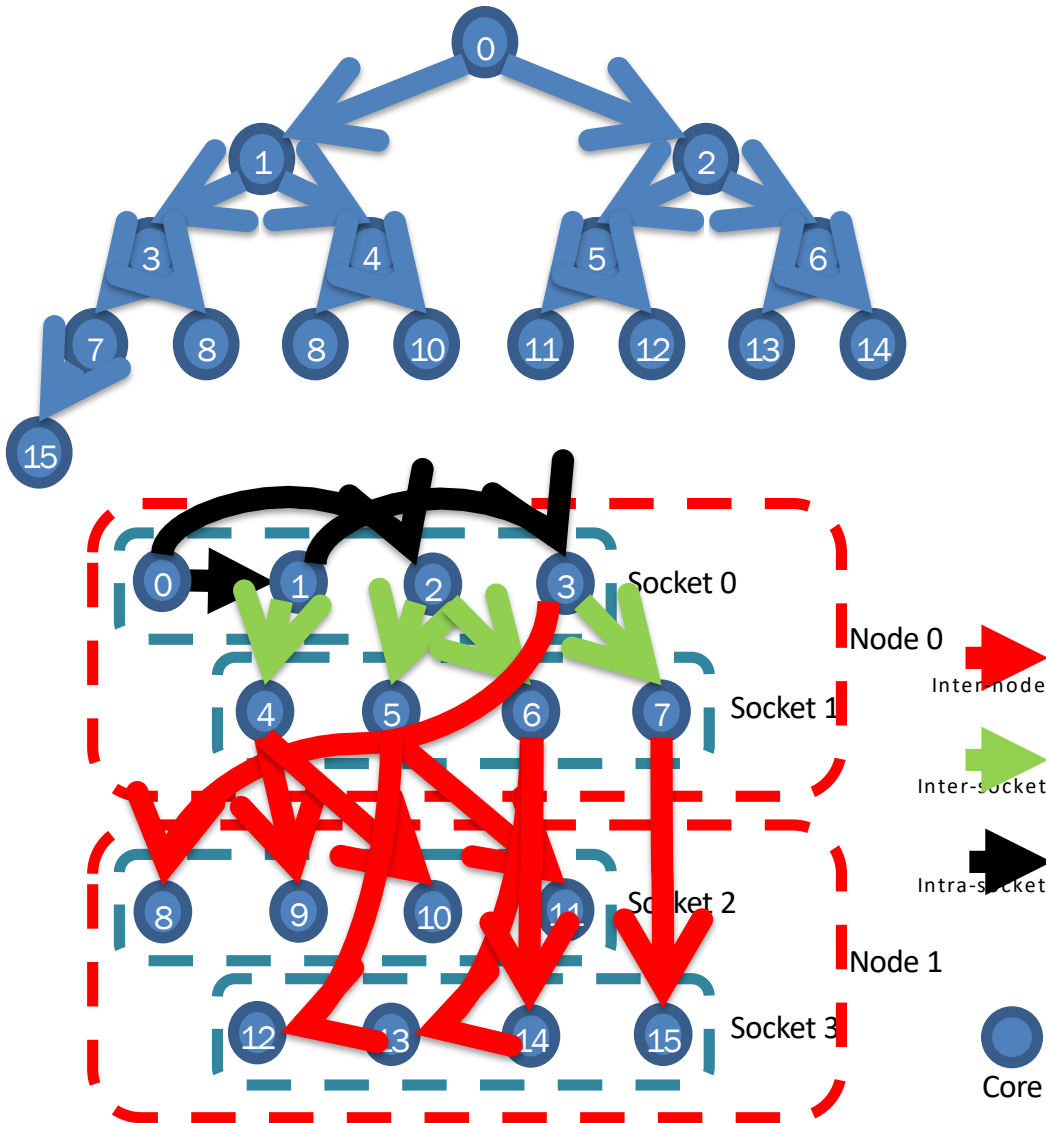
Performance of Broadcast with CPU data varies by noise injection, MSG=4MB(Stampede2)



Performance of Reduce with CPU data varies by noise injection, MSG=4MB(Stampede2)



Network Topology

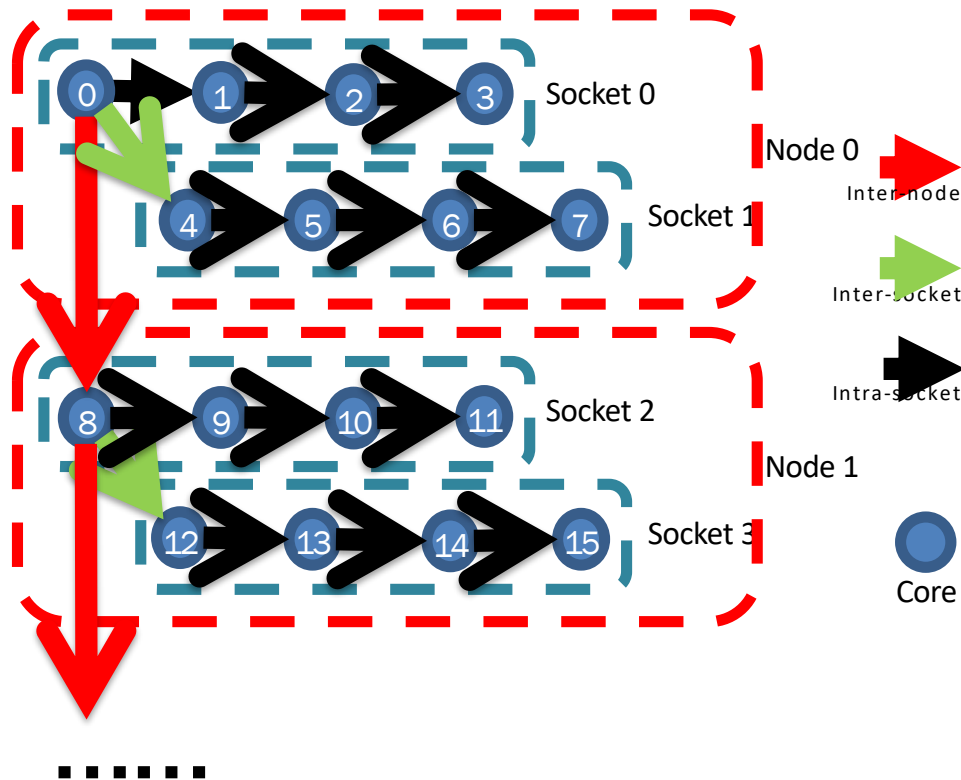


15 P2P communication

8 inter-node communication
4 inter-socket communication
3 intra-socket communication

Topology-aware tree

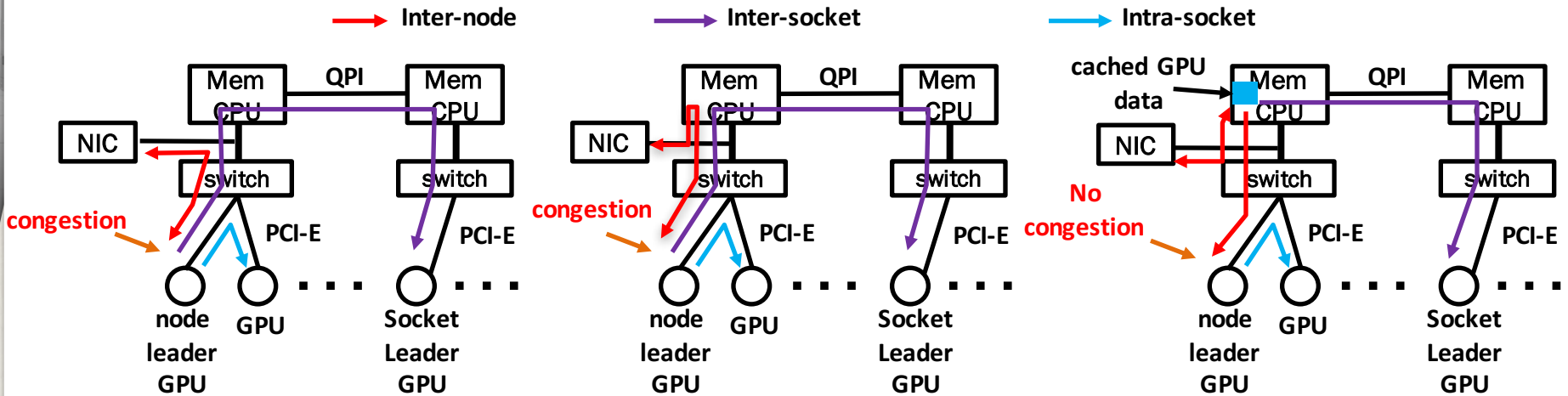
1. Non-blocking P2P
2. ADAPT



1 inter-node communication
2 inter-socket communication
12 intra-socket communication

GPU Optimizations

1. Minimize Communications over PCI-Express

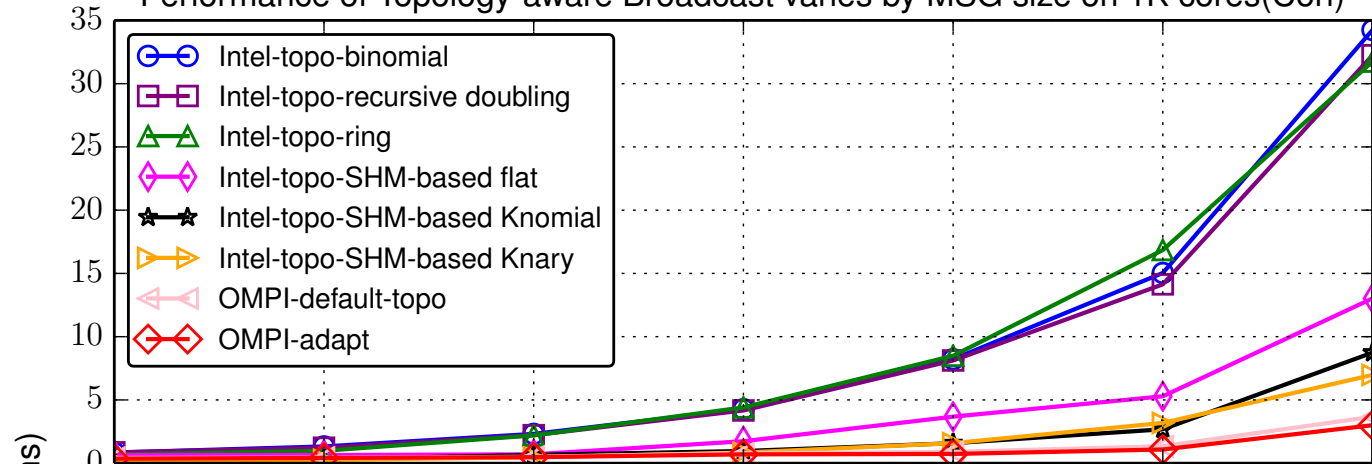


(a) With GPUDirect (b) Without GPUDirect (c)

2. Offload Reduction Operation asynchronously on GPU

Experiments (topology-aware)

Performance of Topology-aware Broadcast varies by MSG size on 1K cores(Cori)

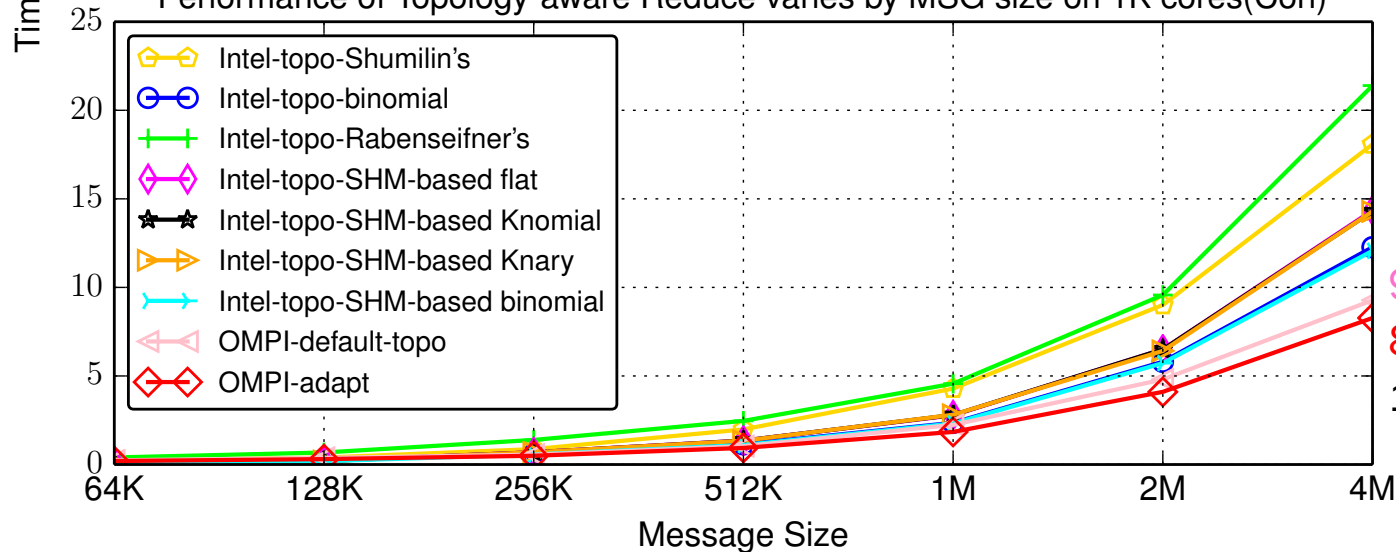


3.671

3.002

1.2X speedup

Performance of Topology-aware Reduce varies by MSG size on 1K cores(Cori)



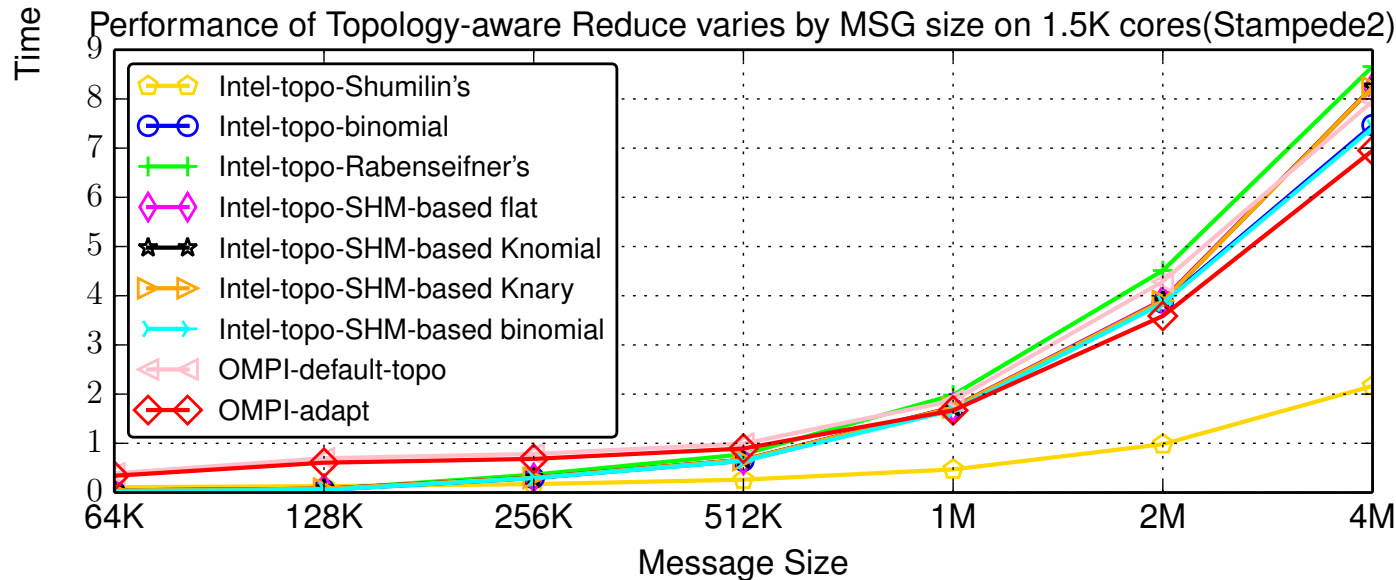
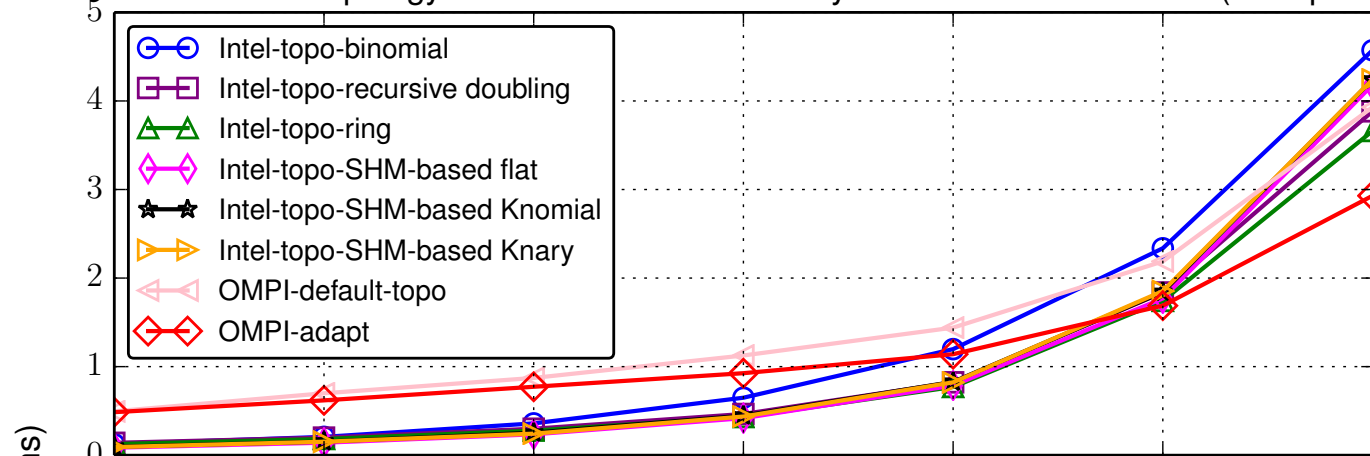
9.274

8.247

1.12X speedup

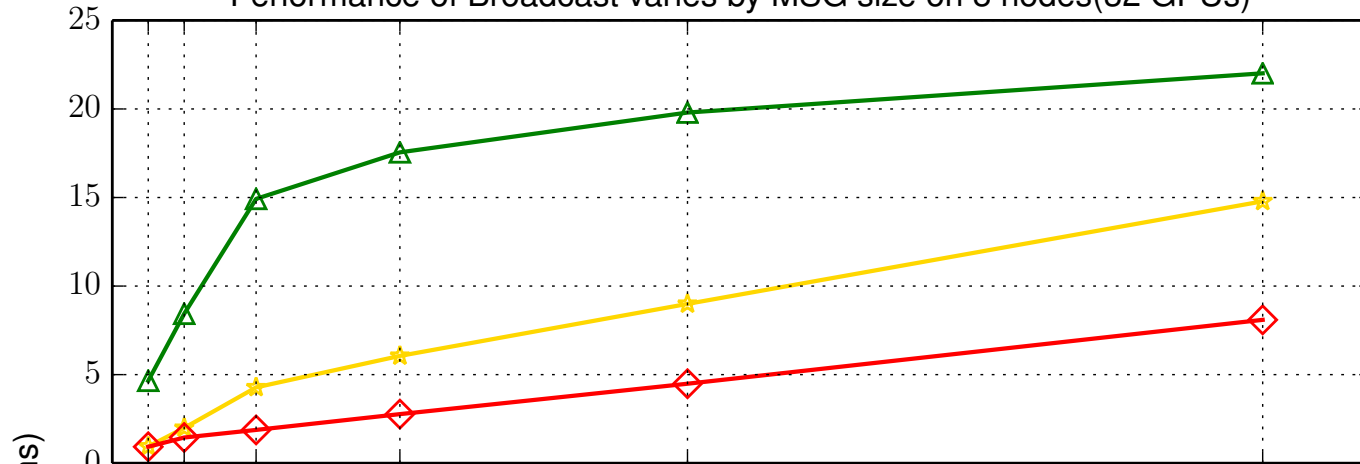
Experiments (topology-aware)

Performance of Topology-aware Broadcast varies by MSG size on 1.5K cores(Stampede2)

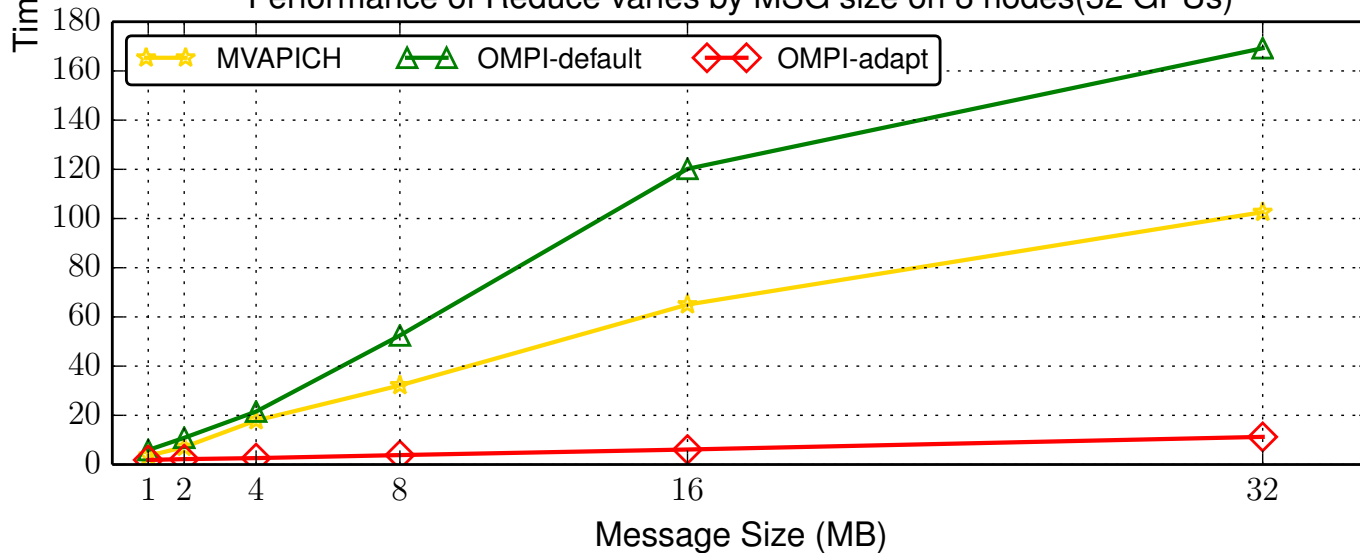


Experiments (GPU)

Performance of Broadcast varies by MSG size on 8 nodes(32 GPUs)



Performance of Reduce varies by MSG size on 8 nodes(32 GPUs)



Experiments (Application)

ASP on Cori (1K cores, problem size 256K, message size 1MB)

	Cray MPI	Intel MPI	OMPI-ADAPT	OMPI-default
Communication (s)	2.98	15.26	1.99	14.18
Total Runtime (s)	6.20	18.46	5.21	17.40
Percentage (%)	48.06%	82.67%	38.20%	81.49%

Conclusion

- Conclusion

- Alleviate the effects of noise by relaxing the synchronizations with an event-driven design.
- Maximize the concurrent communications over different hardware levels to speed up collectives with topology-aware communication trees.
- Enable highly efficient topology-aware NVIDIA GPU collective operations with optimizations.

- Future work

- Support more type of collective operations.
- Integrate with non-blocking collective operations.