

Greedy Trees for MPI Reductions

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Table of Contents

Introduction and Model

Unidirectional

Nonuniform Segmentation

Bidirectional

Conclusion

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Table of Contents

Introduction and Model

Nonuniform Segmentation



What is a reduction?

- We will consider a set of p processors with distributed memory and each processor has a message of size m.
- A reduction combines the messages entry-wise, and returns the value on one specified processor.
- Example: p = 3, m = 5

0	1	2		0		1		2		0
2	1	1		2		1		1		4
4	2	3		4		2		3		9
6	3	5	\rightarrow	6	+*	3	+*	5	\rightarrow	14
8	4	7		8		4		7		19
10	5	9		10		5		9		24

^{*} Can be any associative operation.



Communication Model

- Unidirectional system At any given time a processor is allowed to send a message to another processor or receive a message from another processor, but not both.
- Communication time between two processors is given by the linear model, $\alpha + \beta m$, where α is the latency (start up time) and β is the inverse bandwidth.
- The time for the computation is given γm .
- Cannot overlap communication and computation.
- In practice we have the relationship, $\alpha >> \beta > \gamma$.
- The message m can be split into q segments of size s_i .
- Uniform segmentation: $s_i = s$ for all i.



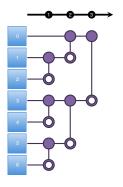
Table of Contents

Unidirectional

Nonuniform Segmentation



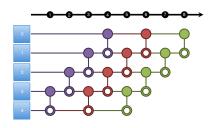
Binomial Tree



- Best for small messages, $\alpha >> \beta m$.
- Minimizes the number of communications started.
- No segmentation. Only increases latency.
- $time = \lceil \log_2 p \rceil (\alpha + \beta m + \gamma m)$



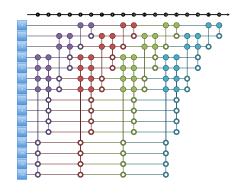
Pipeline Tree



- Best for long messages, $\alpha << \beta m$.
- Poor startup, but optimal overhead for trailing segments.
- time = $((p-1)+2(q-1))(\alpha+\beta s+\gamma s)$



Binary Tree



- At each step, two different processors send to the same receiving processor.
- An iteration is therefore twice as long as compared to the other trees.
- Good for medium sized messages, α ≈ βm.
- $time = (2(\lceil \log_2 p + 1 \rceil 1) + 4(q 1))(\alpha + \beta s + \gamma s)$



Time Complexity for Binomial, Pipeline, and Binary

Binomial	Time	$\lceil \log_2 p \rceil (\alpha + \beta m + \gamma m)$				
	Time	$(p-1)(\alpha+\beta s+\gamma s)+2(q-1)(\alpha+\beta s+\gamma s)$				
Pipeline	$\left(rac{2mlpha}{(p-3)(eta+\gamma)} ight)^{1/2}$					
	T _{opt}	$\left[\left((\rho - 3)\alpha \right)^{1/2} + \left(2m(\beta + \gamma) \right)^{1/2} \right]^2$				
	Time	$2(\lceil log_2(p+1)\rceil - 1)(\alpha + \beta s + \gamma s) + 4(q-1)(\alpha + \beta s + \gamma s)$				
Binary	Sopt	$\left(rac{2mlpha}{({\sf N}-3)(eta+\gamma)} ight)^{1/2}$				
	T _{opt}	$2\left[\left((N-3)\alpha\right)^{1/2}+\left(2m(\beta+\gamma)\right)^{1/2}\right]^{2}$				

 $N = \lceil \log_2(p+1) \rceil$, s_{opt} is the optimal equi-segment size, and T_{opt} is the time for the algorithm at s_{opt} . Formulae are valid for p > 3.

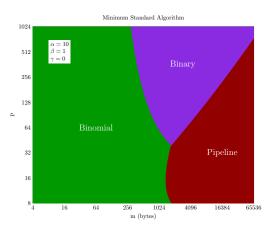


Lower Bounds for each term in communication time

	Latency	Bandwidth	Computation
Reduce	$\lceil \log_2 p \rceil \alpha$	2 m eta	$\frac{p-1}{p}m\gamma$
Binomial	$\lceil \log_2 p \rceil \alpha$	$\lceil \log_2 p \rceil m \beta$	$\lceil \log_2 p \rceil m \gamma$
Pipeline	$(p-1)\alpha$	$(p-3+2m)\beta$	$(p + 2m - 3)\gamma$
Binary	$2(N-1)\alpha$	$2(N-3+2m)\beta$	$2(N-3+2m)\gamma$

$${}^*N = \lceil \log_2(p+1) \rceil$$



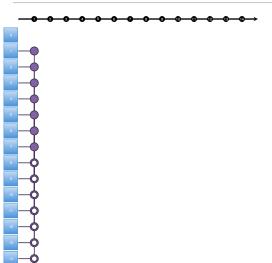


Regions where binomial or pipeline or binary is better in term of the number of processors (p) and the message size (m). For each algorithm, each p and each m, the optimal segment size is used. The machine parameters are $\alpha = 10, \beta = 1, \gamma = 0$.



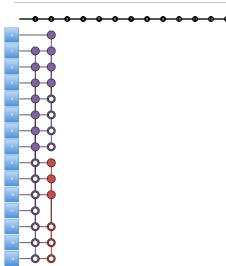
13 of 33

Greedy Tree - Unidirectional, No Computation



- Optimal for uniform segmentation.
- Motivated by greedy QR factorization scheme. [Cosnard and Robert '86]
- Different tree for each segment.
- We assume the operation is commutative (and associative as well, of course).

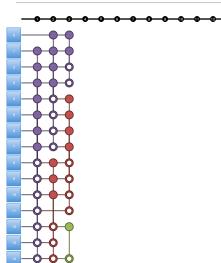




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13 of 33

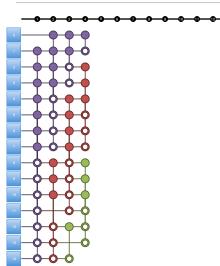




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Greedy trees

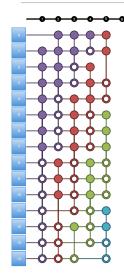




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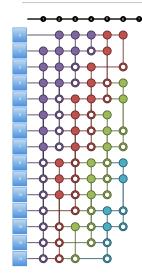
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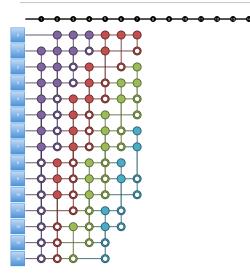
13 of 33

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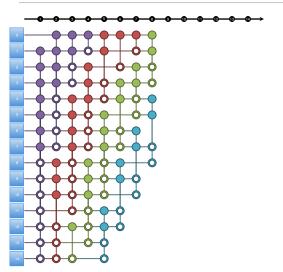




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Greedy trees





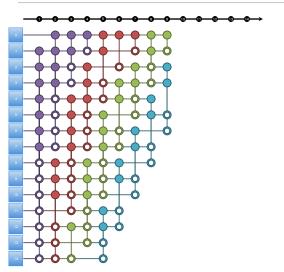
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Greedy trees



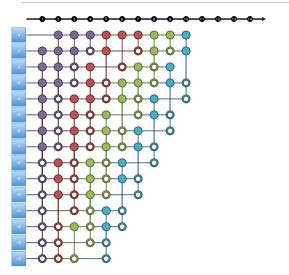
13 of 33

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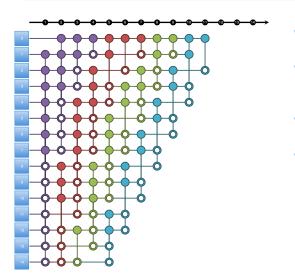




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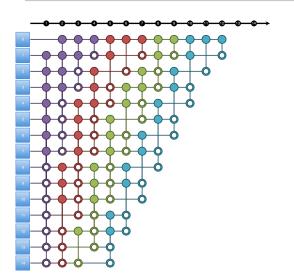
Greedy trees





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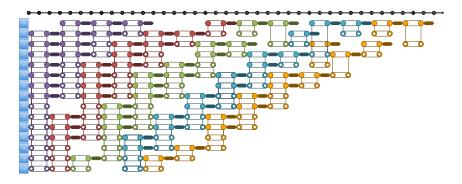


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14 of 33

Greedy Tree - Unidirectional with Computation



15 processors, 5 equi-segments, $t_{comm} = 2$ and $t_{comp} = 1$.

Filled in circles represent receiving processors, open circles represent sending processors, and hexagons represent computation.

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15 of 33

Theoretical Results

Theorem

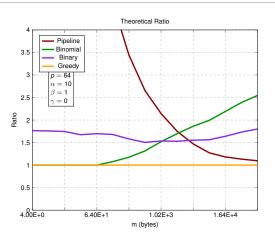
In an unidirectional system assuming that segments are reduced in order the time complexity of the greedy algorithm is no worse than any reduction algorithm.

- Segments do not have to be equal size.
- Reducing segments in order allows for less work space (buffer size is 2 × segment size), also this will work for non-commutative operations.
- Each algorithm is tuned for optimal uniform segmentation.
- For given parameters, $p, m, \alpha, \beta, \gamma$, which algorithm is the best?

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Theoretical Results (ratio)

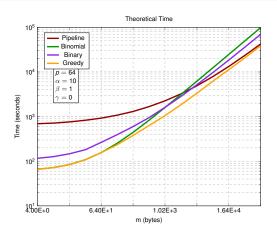


- Each algorithm is tuned for optimal uniform segmentation.
- 50% speed up for "medium sized" messages.

16 of 33



Theoretical Results (time)

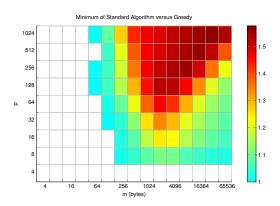


- Each algorithm is tuned for optimal uniform segmentation.
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17 of 33



Theoretical Results (ratio versus best of "standard algorithms")



- Each algorithm is tuned for optimal uniform segmentation.
- 50% speed up for "medium sized" messages.



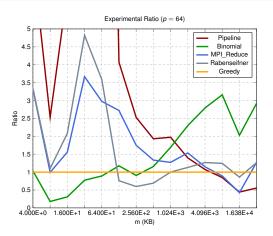
C code for the unidirectional greedy reduction algorithm.

```
int global_s;
int Reduce greedy/ void *sendbuf notype, void *recybuf notype, int m.
        MPI Datatype mpi datatype, MPI Op mpi op, int root, MPI Comm mpi comm) (
        int pool size:
        int my rank:
        int j, i, q, z, s2, s3,qstart, qend, snext; int s=qlobal s;
        MDT Status status
        int *tempbuf, *tempbuf2;
        int *sendbuf, *recybuf;
        sendbuf = (int *) sendbuf notype;
        recybuf = (int *) recybuf notype:
        if (root != 0 ) MPI_Abort( mpi_comm, 512);
        MPI Comm size(mpi comm. &pool size): MPI Comm rank(mpi comm. &my rank):
        if(my rank != 0 ) tempbuf = (int*)mallor(s*sizeof(int));
        tempbuf2 = (int*)malloc(s*sizeof(int));
        if ( my rank == 0)
                 for(i=0;i<n;i++) recvbuf[i] = sendbuf[i];
                for(i=0;i<a;i++) tempbuf[i] = sendbuf[i];</pre>
        a = m/+-
        if( (m % s) 1= 0 )( s2 = m % s; c++;)
        else s2 - s:
        hist = (int *)malloc(c*sizeof(int)):
        for(i = 0: i < a: i++) hist[i] = pool size:
        gstart = 0:
        while( hist[q-1] > 1 )(
                if (qstart != q-1 && hist[qstart+1]-hist[qstart] > 1){ qstart++;
                 for(i = qstart; i >= qend; i--)(
                        z = (i == 0) 7 hist[0]/2 : (hist[i]-hist[i-1])/2;
                        #3 = ( i == q-1 ) 7 #2 : #;
if( my rank < hist[i] 66 my rank >= hist[i] - x )(
                                 MPI Send(tempbuf, s3, mpi datatype, my rank-z, 512, mpi comm );
                                 if( i < e-1 )(
                                         snext = (i == q-2) 7 s2 : s:
                                         for(i=0:i<anext:i++) tempbuf[i] = sendbuf[(i+1)*s + i]:
                         if( my_rank < hist[i] - z && my_rank >= hist[i] - 2*z ){
                                 MPI Recv( tempbuf2, s3, mpi datatype, my rank+z, 512, mpi comm, &status );
                                 if ( my_rank == 0 )(
                                         for( j = 0; j < x3; j++ ){ recvbuf[i*x + j] += tempbuf2[j];
                                         for( i = 0: i < s3: i++) tempbuf(i) += tempbuf2(i):
                        histfil -- z:
                        if (hist(i) -- 1)(
                                  hist[i] = 0: gend++:
        free( hist ); if(my rank != 0) free( tempbuf ); free( tempbuf2 );
```

- global_s is the size of a segment and needs to be initialized (if possible "tuned") in advance.
- The implementation is restricted to root being 0, MPI_Datatype being int, and MPI_Op being +. These restrictions are not a consequence of the algorithm and can be removed.



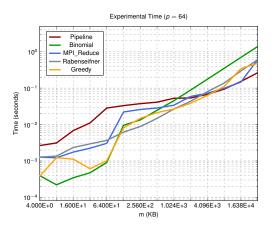
Experimental Results (ratio)



Implemented with OpenMPI v1.4.3 point-to-point functions MPI_Send and MPI_Recv.



Experimental Results (time)



Implemented with OpenMPI v1.4.3 point-to-point functions MPI_Send and MPI_Recv.



Table of Contents

Nonuniform Segmentation



23 of 33

Nonuniform Segmentation

(Note: our algorithm is optimal no matter the segmentation, uniform or not.) Why does segmentation have to be uniform?

- Experiment: Fix the message size to m = 10 and check all possible segmentations.
- Results for greedy
 - 61 of the 986 total trials where optimized by a nonuniform segmentation.
 - The maximum improvement of nonuniform versus uniform segmentation was 7.3%.
 - Of the 61 trials optimized by a nonuniform segmentation the average improvement was 2%.
- For pipeline, all trials where optimized by uniform segmentation.

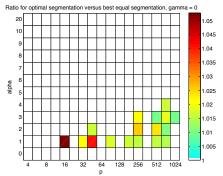
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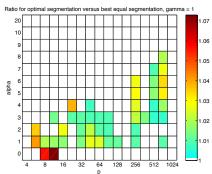


Nonuniform Segmentation

Sample Segmentations:

Parameters	Percent	Best Uniform	Optimal	
$p = 12, \alpha = 0, \beta = 1, \gamma = 1$	7.3%	(1,1,1,1,1,1,1,1,1)	(2,2,1,1,1,1,1,1)	
$p = 48, \alpha = 1, \beta = 1, \gamma = 1$	2.6%	(2,2,2,2,2)	(3,2,2,2,1)	
			(2,2,1,2,2,1)	
$p = 256, \alpha = 5, \beta = 1, \gamma = 1$	3.0%	(4,4,2)	(5,3,2)	





24 of 33



Table of Contents

Nonuniform Segmentation

Bidirectional

25 of 33

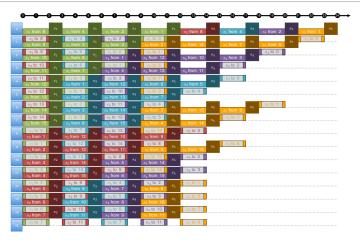


Bidirectional

- Adapt the unidirectional greedy algorithm to the bidirectional context.
- Reduction and broadcast are essentially the same in bidirectional context. (All processors are performing computation.)
- Optimal broadcast algorithm [Traff and Ripke '08, Bar-Noy and Kipnis '94] scheduled in reverse has time ($\lceil \log_2 p \rceil + q - 1$)($t_{comm} + t_{comp}$).
- Bidirectional greedy has same time complexity (conjecture).
- Rabenseifner ['04] provides algorithm for optimal computation.



Bidirectional Greedy Tree with computation



16 processors, 5 equi-segments, $t_{comm} = 2$ and $t_{comp} = 1$. Solid rectangles represent receiving processors and rectangles with end strips represent sending processors. The darker rectangles represent computation.

27 of 33



Pseudo-code for bidirectional greedy algorithm

```
Algorithm 2: Bidirectional Greedy Algorithm
  R = zeros(p, 1);
  C = zeros(p, 2);
  t = 0:
  M = zeros(p, q):
  while \min\{M(i, j) \mid 1 \le i \le p \text{ and } 1 \le j \le q\} = 0 do
       segStart = min\{j \mid M(1, j) = 0\};
        stop = 1;
        j = segStart - 1;
        while stop do
             j \leftarrow j + i,

COMP = \{i \mid C(i, 1) \le t < C(i, 2) \text{ or } t + t_{comm}(j) > C(i)\};
             I = \{i \mid M(i, j) = 0\};

sendProc = I \setminus COMP \setminus \{i \mid S(i) > t\};
             recvProc = I \setminus COMP \setminus \{i \mid R(i) > t\};
             freeProc = sendProc ∩ recvProc;
              sendProc \leftarrow sendProc \setminus freeProc
             recvProc ← recvProc \ freeProc;
             s = |sendProc|:
             r = |recvProc|;
              f = |freeProc|:
              if s = r then
                   y = \lfloor f/z \rfloor,

sendProc \leftarrow sendProc \cup \{freeProc(i) \mid f - y + 1 \le i \le f\};
                   recvProc \leftarrow recvProc \bigcup \{freeProc(i) \mid 1 \le i \le y\};
             else if a crthen
                   m = \min(f, y);
                   if m > 0 then
                    sendProc \leftarrow sendProc[]{freeProc(i) | (f - (m + x) + 1 \le i \le f};
                   if x > 0 then
                    L recvProc ← recvProc ∪{freeProc(i) | 1 ≤ i ≤ x};
             else if \tau < s then
                   m = \min(f, y):
                   x = |(f - m)/2|;
                   if m > 0 then
                    | recvProc ← recvProc | | {freeProc(i) | 1 ≤ i ≤ m + x};
                   if x > 0 then
                    sendProc \leftarrow sendProc \bigcup {freeProc(i) \mid f - x + 1 \le i \le f};
             l = min(|sendProc|, |recvProc)
             if l = 0 then
                   sendProc \leftarrow \emptyset;
                   recvProc \leftarrow \emptyset:
                   sendProc = \{sendProc(i) \mid 1 \le i \le l\};
                   recvProc = \{recvProc(i) | 1 \le i \le l\}:
              M(i, j) = t + t_{comm}(j), \forall i \text{ s.t. } i \in \text{sendProc};
              S(i) = t + t_{comm}(i), \forall i \text{ s.t. } i \in \text{sendProc}:
              R(i) = t + t_{comm}(j) + t_{comp}(j), \forall i \text{ s.t. } i \in \text{recvProc};
             C(i, 1) = t + t_{comm}(j), \forall i \text{ s.t. } i \in \text{recvProc};
             if |\{i \mid M(i, j) = 0\}| = 1 then
              M(1, j) = max(\{M(i, j) | 1 \le ilep\}) + t_{comp}(j);
             if |\{i \mid S(i) \le t\}| + |\{i \mid R(i) \le t\}| < 2 then

| stop = 0:
             else if i \ge a then
              L stop = 0;
```

28 of 33



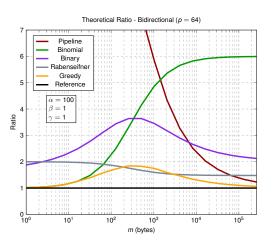
Lower bounds for each term in communication time

	Latency	Bandwidth	Computation
Reduce	$\lceil log_2p \rceil \alpha$	meta	$\frac{p-1}{p}m\gamma$
Binomial	$\lceil \log_2 p \rceil \alpha$	$\lceil \log_2 p \rceil m \beta$	$\lceil \log_2 p \rceil m \gamma$
Pipeline	$(p-1)\alpha$	$(p-3+m)\beta$	$(p-3+m)\gamma$
Binary	$2(N-1)\alpha$	$(N-3+2m)\beta$	$(N-3+2m)\gamma$

$${}^*N = \lceil \log_2(p+1) \rceil$$



Theoretical Results (ratio)

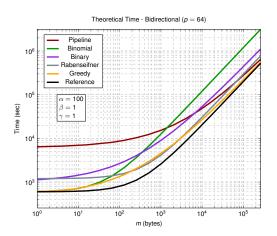


Reference Line: $\lceil \log_2 p \rceil \alpha + m\beta + \frac{p-1}{p} \gamma$

30 of 33



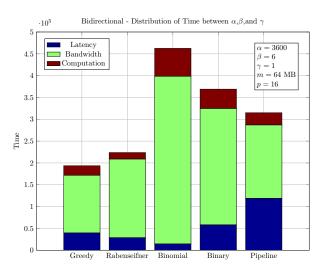
Theoretical Results (time)



Reference Line: $\lceil \log_2 p \rceil \alpha + m\beta + \frac{p-1}{p} \gamma$

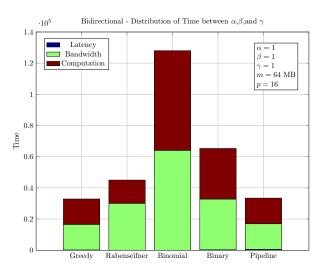


Distribution of time between α , β , γ



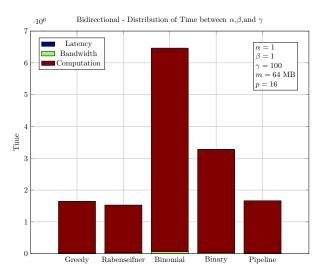


Distribution of time between α , β , γ





Distribution of time between α , β , γ





Conclusion

Unidirectional:

- Compared the greedy reduction with three standard algorithms.
- Greedy was the best theoretically.
- Most improvement is for medium sized messages (1Kb 1Mb).
- Nonuniform segmentation is considered.
- Greedy is optimized by nonuniform segmentation for some machine parameters.

Bidirectional:

- Adapt unidirectional greedy algorithm for a bidirectional system
- Same time complexity of optimal broadcast algorithm.
- Implementation coming soon...

Questions?